

Guaranteeing the homotopy type of a set defined by non-linear inequalities.

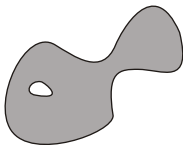
Nicolas Delanoue

Topological Methods For The Study Of Discrete Structures

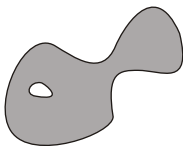
February 2010

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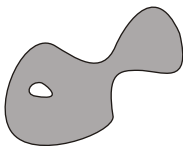


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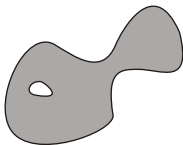
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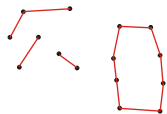
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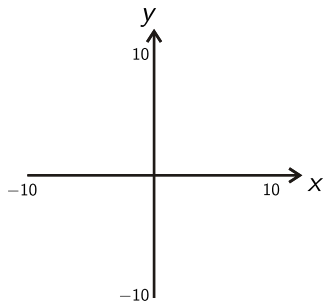


Outline

- 1 Introduction to interval analysis
- 2 Motivation - topological recall
- 3 Computing the number of connected components
 - A sufficient condition for proving that a set is star-shaped
 - The idea
- 4 More topological information
- 5 What I am doing now

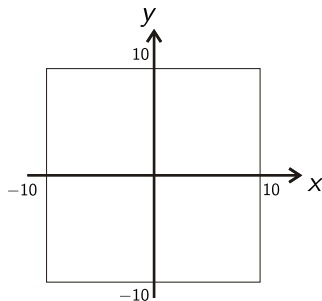
Example 1

$$\mathbb{S} = \{(x, y) \in [-10; 10]^2 \mid f(x, y) = x^2 + y^2 + xy - 30 \leq 0\}$$



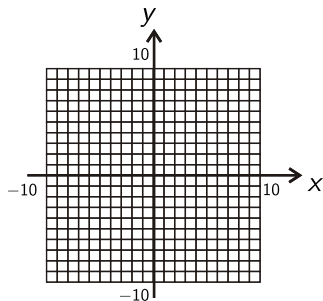
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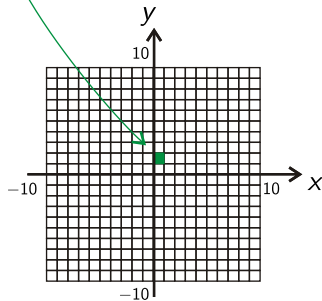


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$$\mathbb{S} = \{(x, y) \in [-10; 10]^2 \mid f(x, y) = x^2 + y^2 + xy - 30 \leq 0\}$$

$$x \in [0; 1]$$

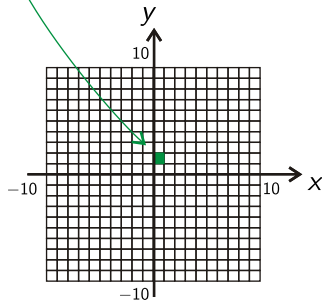
$$y \in [1; 2]$$



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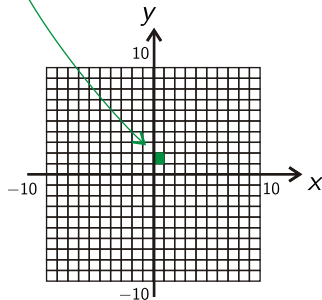
$$\begin{aligned} x \in [0; 1] &\Rightarrow x^2 \in [0; 1] \\ y \in [1; 2] & \end{aligned}$$



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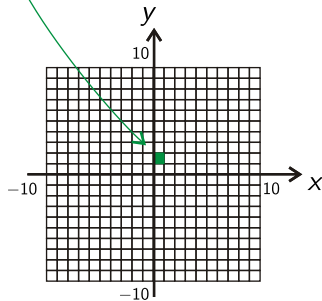
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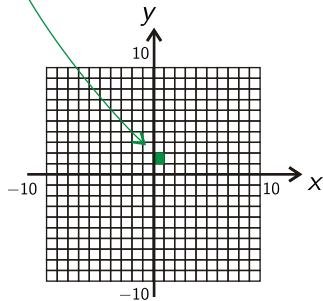
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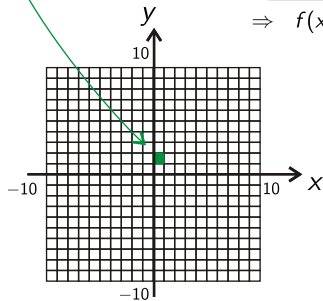
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$$\Rightarrow \quad f(x, y) \in [-29; -27]$$



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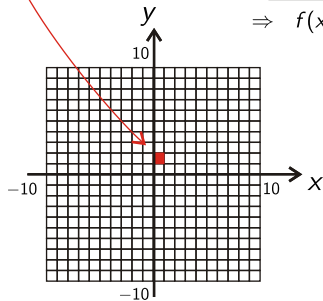
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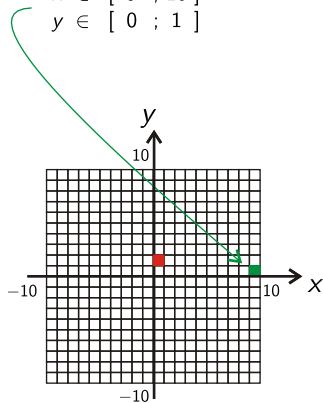


Example 1

$$\mathbb{S} = \{(x, y) \in [-10; 10]^2 \mid f(x, y) = x^2 + y^2 + xy - 30 \leq 0\}$$

$$x \in [9; 10]$$

$$y \in [0; 1]$$



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$$x \in [9; 10]$$

$$\Rightarrow x^2 \in [81; 100]$$

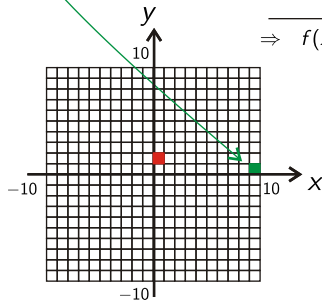
$$y \in [0; 1]$$

$$\Rightarrow y^2 \in [0; 1]$$

$$\Rightarrow xy \in [0; 10]$$

$$\Rightarrow -30 \in [-30; -30]$$

$$\Rightarrow f(x, y) \in [51; 81]$$



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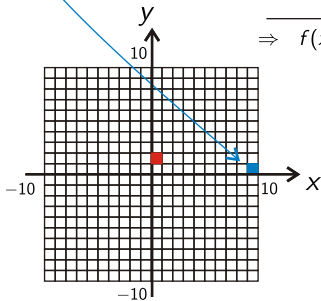
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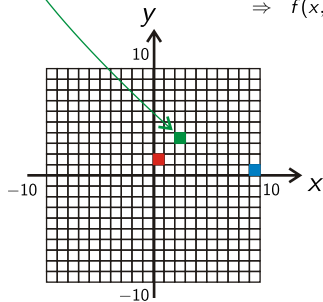


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$$\begin{array}{lcl} x \in [2; 3] & \Rightarrow & x^2 \in [4; 9] \\ y \in [3; 4] & \Rightarrow & y^2 \in [9; 16] \\ & \Rightarrow & xy \in [6; 12] \\ & \Rightarrow & -30 \in [-30; -30] \end{array}$$

$$\Rightarrow f(x, y) \in [-11; 7]$$

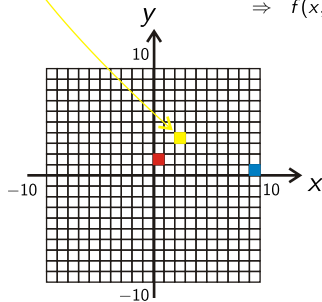


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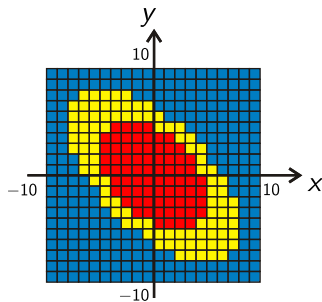
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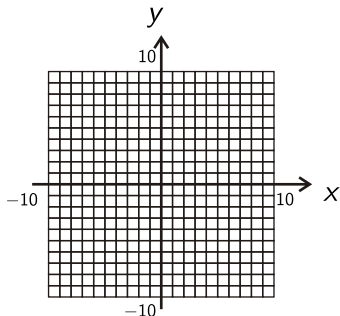
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$$\mathbb{S} = \{(x, y) \in [-10; 10]^2 \mid f(x, y) = x^2 + y^2 + xy - 30 \leq 0\}$$

Proving that an equation has no solution

Example 2

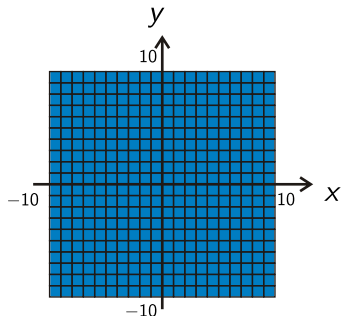
$$S' = \{(x, y) \in [-10; 10]^2 \mid f'(x, y) = x^2 + y^2 + xy + 10 \leq 0\}$$



Proving that an equation has no solution

Example 2

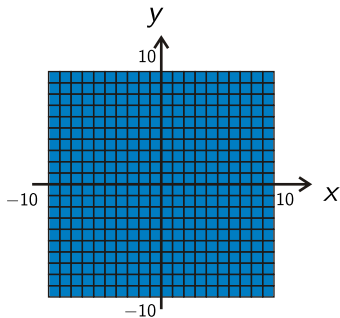
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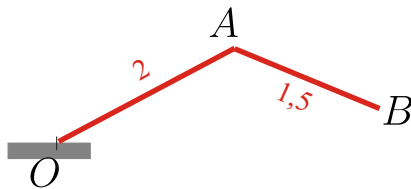
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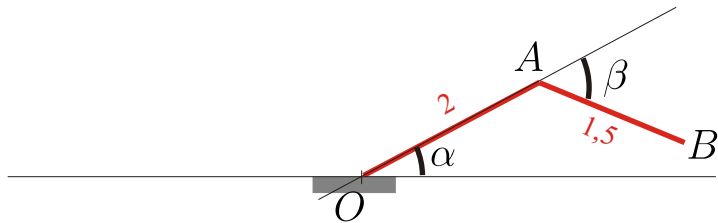
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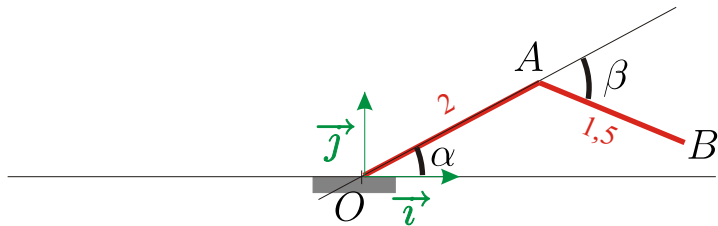
$$S' = \{(x, y) \in [-10; 10]^2 \mid f'(x, y) = x^2 + y^2 + xy + 10 \leq 0\}$$

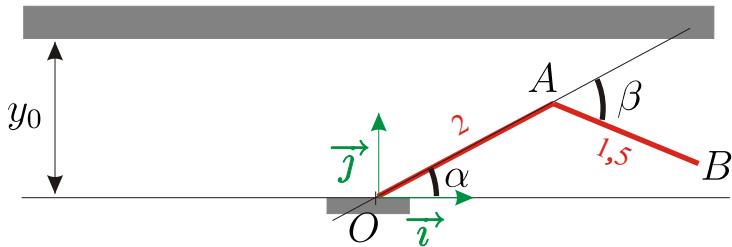


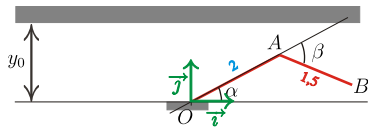
$$\Rightarrow S' = \emptyset$$

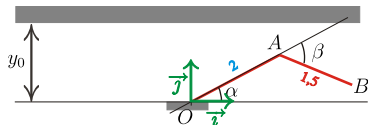






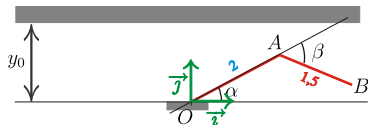






Coordinates of A

$$\begin{cases} x_A = 2 \cos(\alpha) \\ y_A = 2 \sin(\alpha) \end{cases}$$

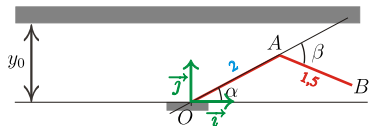


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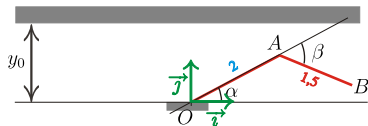
Coordinates of B

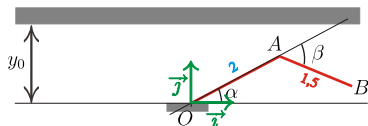
$$\begin{cases} x_B = 2 \cos(\alpha) + 1.5 \cos(\alpha + \beta) \\ y_B = 2 \sin(\alpha) + 1.5 \sin(\alpha + \beta) \end{cases}$$



Constraints

$$y_A \in [0, y_0]$$





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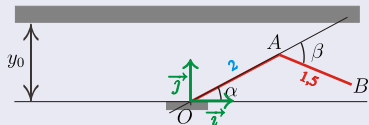
$$y_A \in [0, y_0]$$

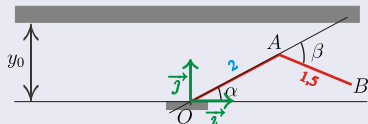
Constraints

$$y_B \in]-\infty, y_0]$$

Constraints about α and β

$$\alpha \in [-\pi, \pi], \beta \in [-\pi, \pi]$$





Feasible configuration set

$$(\alpha, \beta) \in [-\pi, \pi]^2 /$$

$$\begin{cases} f_1(\alpha, \beta) = 2 \sin(\alpha) - y_0 & \leq 0 \\ f_2(\alpha, \beta) = -2 \sin(\alpha) & \leq 0 \\ f_3(\alpha, \beta) = 2 \sin(\alpha) + 1.5 \sin(\alpha + \beta) - y_0 & \leq 0 \end{cases}$$

Definition (*path-connected set*)

A topological space \mathbb{S} is *path-connected* if and only if for every two points $x, y \in \mathbb{S}$, there is a continuous function f from $[0, 1]$ to \mathbb{S} such that $f(0) = x$ and $f(1) = y$.

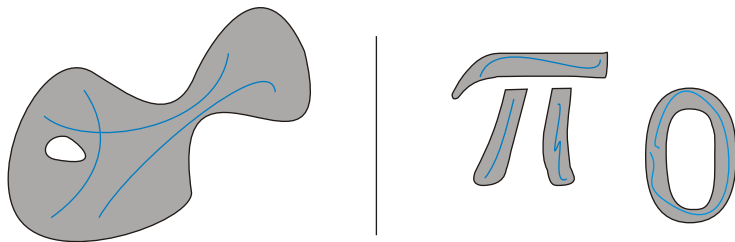
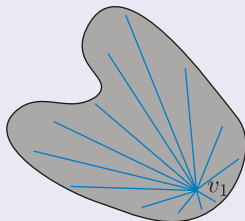


FIG.: Examples.

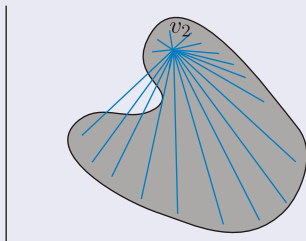
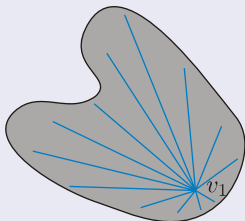
Definition (*star*)

The point v^* is a *star* for a subset X of an Euclidean space if $\forall x \in X$, the segment $[x, v^*]$ is include in X .



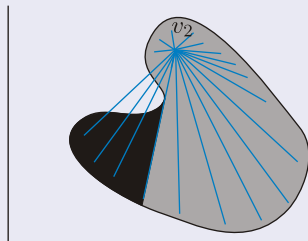
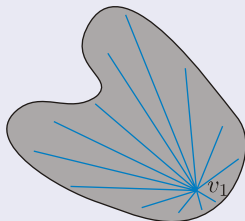
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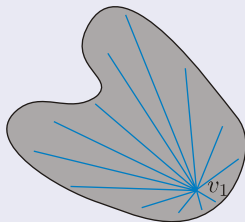
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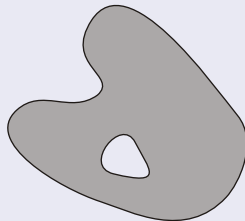
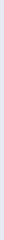
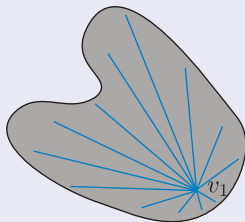
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If there exists $v^* \in X$ such that v^* is a star for X , then we say that X is *star-shaped* or v^* -*star-shaped*.



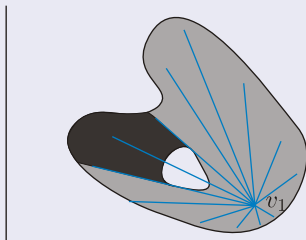
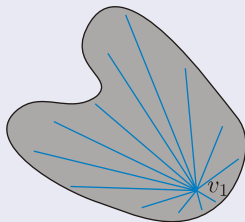
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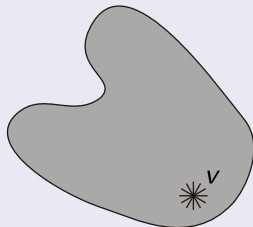
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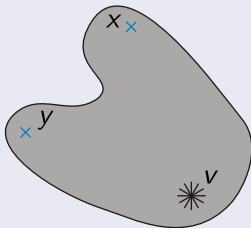
Proposition 1

A star-shaped set is a path-connected set.



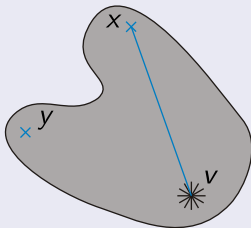
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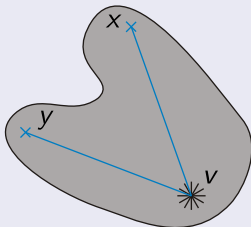
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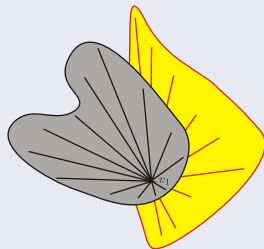
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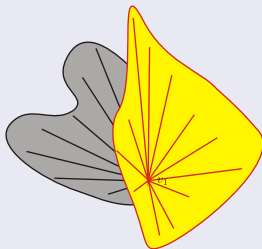
Proposition 2

Let X and Y two v^* -star-shaped set, then $X \cap Y$ and $X \cup Y$ are also v^* -star-shaped.



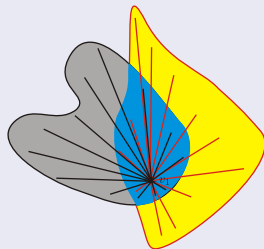
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Let us prove that $v^* = (0.6, -0.5)$ is a star for the set defined by

$$\mathbb{S} = \{(x, y) \in \mathbb{R}^2, \text{ such that } f(x, y) = x^2 + y^2 + xy - 2 \leq 0\}$$

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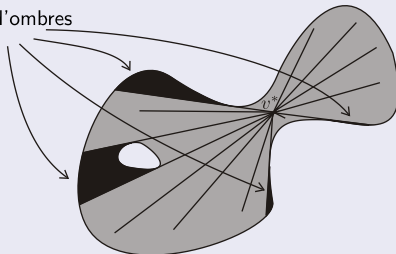
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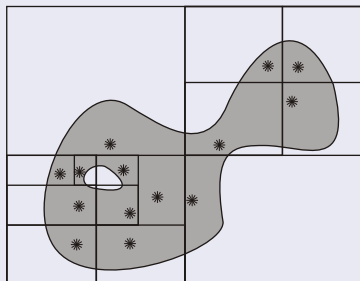
$$\Leftrightarrow \begin{cases} x^2 + y^2 + xy - 2 = 0 \\ (2x + y)(x - 0.6) + (2y + x)(y + 0.5) \leq 0 \end{cases} \text{ is inconsistent}$$

Zones d'ombres



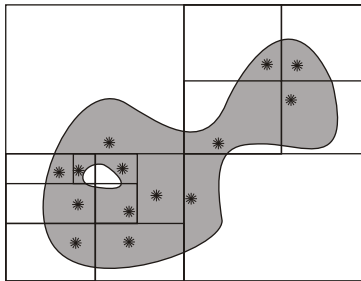
The idea

To divide it with a paving \mathcal{P} such that, on each part p , $S \cap p$ is star-shaped.



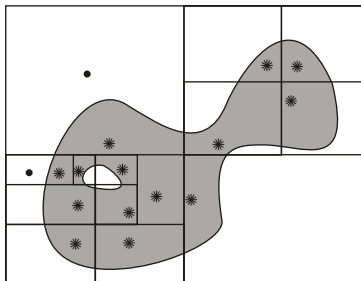
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Let us define the notion of *star-spangled* graph with the relation :
 $S \cap p \cap q \neq \emptyset$.



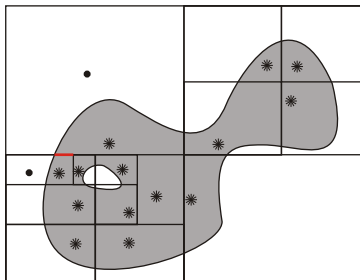
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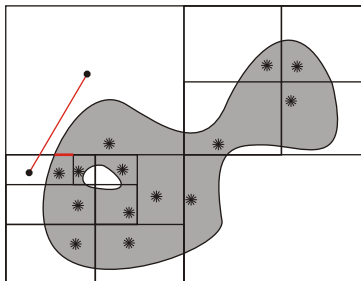
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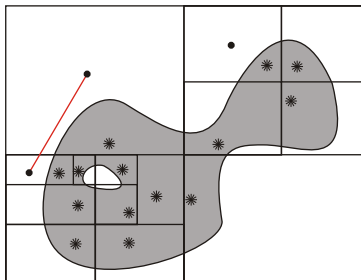
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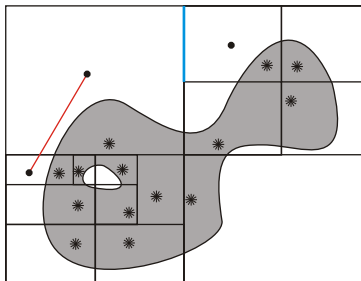
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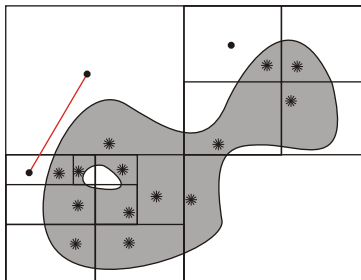
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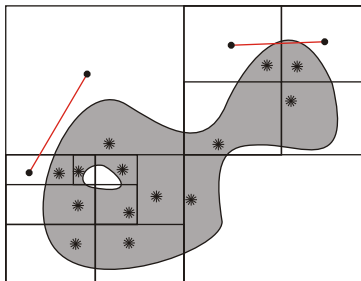
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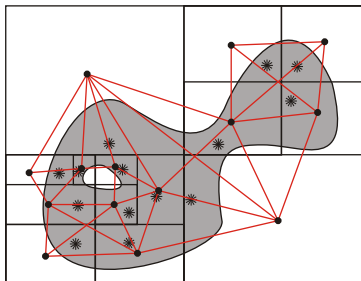
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Let us define the notion of *star-spangled* graph with the relation :
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The idea

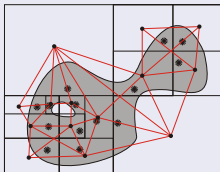
Let us define the notion of *star-spangled* graph with the relation :
 $S \cap p \cap q \neq \emptyset$.



Definition

A *star-spangled graph* of a set \mathbb{S} , noted by $\mathcal{G}_{\mathbb{S}}$, is a relation \mathcal{R} on a paving \mathcal{P} where

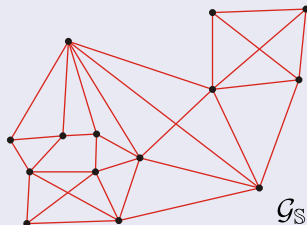
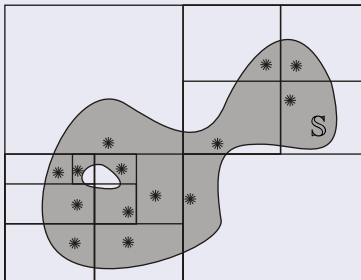
- $\mathcal{P} = (p_i)_{i \in I}$, for all p of \mathcal{P} , $\mathbb{S} \cap p$ is star-shaped. And $\mathbb{S} \subset \bigcup_{i \in I} p_i$
- \mathcal{R} is the reflexive and symmetric relation on \mathcal{P} defined by $p \mathcal{R} q \Leftrightarrow \mathbb{S} \cap p \cap q \neq \emptyset$.



Theorem

Let \mathcal{G}_S be a star-spangled graph of a set S .

S is path-connected $\Leftrightarrow \mathcal{G}_S$ is connected .



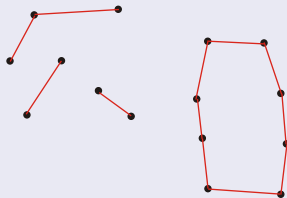
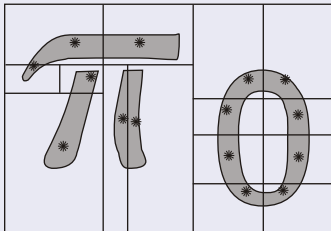
▶ proof

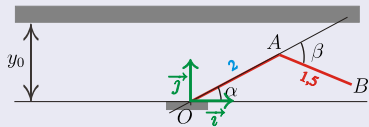
Corollary

Let $\mathcal{G}_{\mathbb{S}}$ be a star-spangled graph of a set \mathbb{S} .

$\mathcal{G}_{\mathbb{S}}$ has the same number of connected components than \mathbb{S} . i.e.

$$\pi_0(\mathbb{S}) = \pi_0(\mathcal{G}_{\mathbb{S}}).$$



Feasible configuration set, $y_0 = 2.3$ 

$$\mathbb{S} = \left\{ (\alpha, \beta) \in] - \pi, \pi[\right. / \left. \left\{ \begin{array}{l} 2 \sin(\alpha) \in [0, y_0] \\ 2 \sin(\alpha) + 1.5 \sin(\alpha + \beta) \in] - \infty, y_0] \end{array} \right\} \right\}$$

The solver CIA (path-Connected via Interval Analysis)

Feasible configuration set, $y_0 = 2.3$

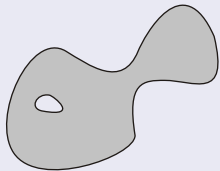
$$\mathbb{S} = \left\{ (\alpha, \beta) \in]-\pi, \pi[^2 / \left\{ \begin{array}{l} 2 \sin(\alpha) \in [0, y_0] \\ 2 \sin(\alpha) + 1.5 \sin(\alpha + \beta) \in]-\infty, y_0] \end{array} \right. \right\}$$

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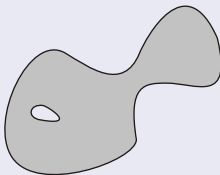
$$(\alpha, \beta) \in]-\pi, \pi[^2 /$$

$$\left\{ \begin{array}{l} f_1(\alpha, \beta) = 2 \sin(\alpha) - y_0 \leq 0 \\ f_2(\alpha, \beta) = -2 \sin(\alpha) \leq 0 \\ f_3(\alpha, \beta) = 2 \sin(\alpha) + 1.5 \sin(\alpha + \beta) - y_0 \leq 0 \end{array} \right.$$

C.I.A. :



H.I.A. :



topological invariant

number of connected components

Let π_0 be :

$$\pi_0 : \begin{array}{ccc} \{ \text{"Nice" sets} \} & \rightarrow & \mathbb{N} \\ X & \mapsto & \text{number of connected components of } X \end{array}$$

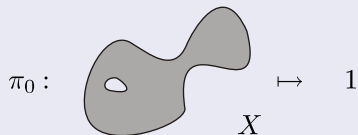


FIG.: $\pi_0(X)$ and $\pi_0(Y)$.

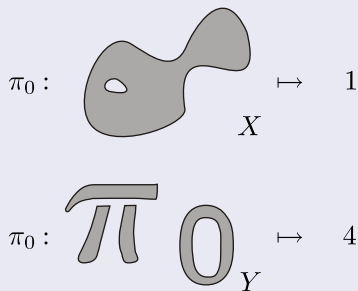


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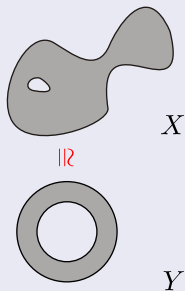


FIG.: $\pi_0(\cdot)$ is a topological invariant.

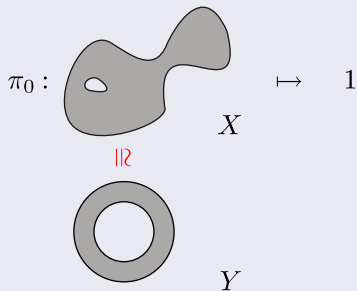


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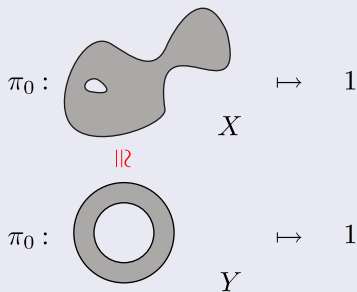


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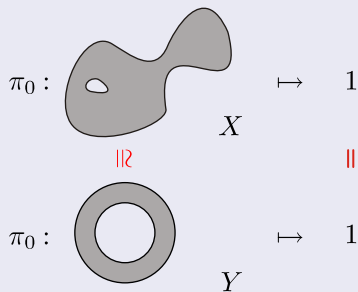


FIG.: $\pi_0(\cdot)$ is a topological invariant.

$\pi_0(\cdot)$ is a topological invariant since

$$\text{If } X \cong Y \text{ then } \pi_0(X) = \pi_0(Y)$$

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$$\text{If } X \cong Y \text{ then } \pi_0(X) = \pi_0(Y)$$

If X and Y are such that $\pi_0(X) \neq \pi_0(Y)$
then $X \not\cong Y$.

There exists sets such that

$$X \not\cong Y \text{ and } \pi_0(X) = \pi_0(Y)$$

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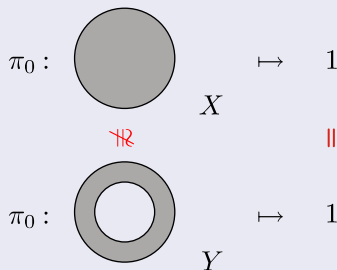


FIG.: $\pi_0(\cdot)$ is not enough strong.

Definition - Homeomorphism

A function f between two topological spaces X and Y is called a homeomorphism if it has the following properties :

- 1 f is a bijection (1-1 and onto),

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Definition - homeomorphic spaces

Two spaces X and Y with a homeomorphism $f : X \rightarrow Y$ between them are called homeomorphic. From a topological viewpoint they are the same.

Examples

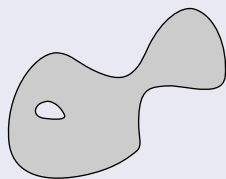
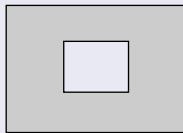
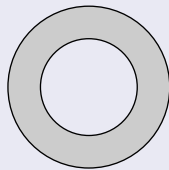
 X  Y  Z

FIG.: Example.

Examples

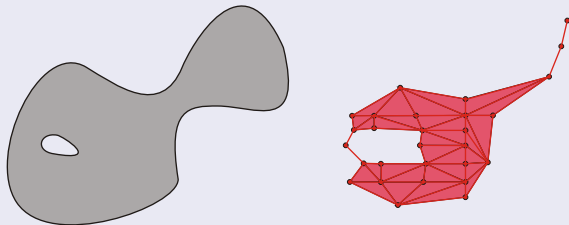
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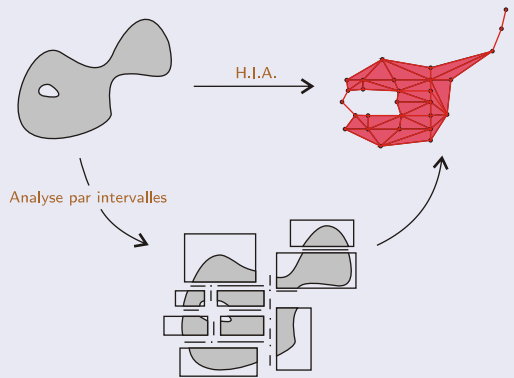
$$X \cong Y \cong Z.$$

Examples

Example.

- Create a **triangulation** to obtain more topological properties.
 - homotopy type, fundamental group ($\pi_1(\mathbb{S})$).
 - homology groups ($H_1(\mathbb{S}), H_2(\mathbb{S}), \dots$).
 - Betti numbers.





Definition - homotopy between the two functions

Two continuous functions $f, g : X \rightarrow Y$ are *homotopic*, $f \sim g$ if there exists a continuous function $F : X \times [0, 1] \rightarrow Y$, such that :

$$F(x, 0) = f(x) \text{ and } F(x, 1) = g(x), \forall x \in X.$$

Introduction to interval analysis

Motivation - topological recall

Computing the number of connected components

More topological information

What I am doing now

topological invariant

The fundamental group

homotopy equivalence between spaces

Triangulation

Create a triangulation

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$$f \sim f^0$$

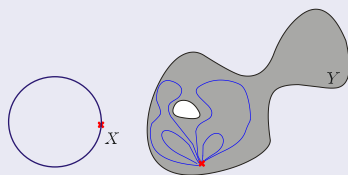


FIG.:

Definition : π_1 of a set

Let Y be a path connected space and $y_0 \in Y$,

$$\pi_1(Y, y_0) = \{f : \mathbb{S}_1 \rightarrow Y, f \text{ continuous}, f(x_0) = y_0\} / \sim$$

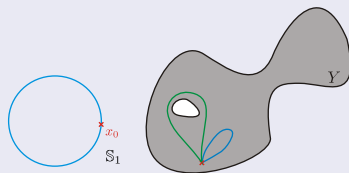


FIG.: f^1 and f^0 .

Poincaré, H. 'Analysis situs', J. Ecole polytech. (2)1, 1-121 (1895).

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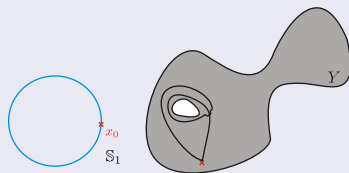


FIG.: f^2

Poincaré, H. 'Analysis situs', J. Ecole polytech. (2)1, 1-121 (1895).

Property

$\pi_1(Y, y_0)$ is a group.

$$f^0 \times f^1 \sim f^1.$$

Property

$\pi_1(Y, y_0)$ is a group.

$$f^1 \times f^{-1} \sim f^0$$

$$\pi_1 : \text{[circle]} \mapsto \{0\}$$

X

FIG.: $\pi_1(\cdot)$ is a topological invariant.

$$\begin{array}{ccc} \pi_1 : \text{[Disk]} & \mapsto & \{0\} \\ & & X \\ \pi_1 : \text{[Annulus]} & \mapsto & \mathbb{Z} \\ & & Y \end{array}$$

FIG.: $\pi_1(\cdot)$ is a topological invariant.

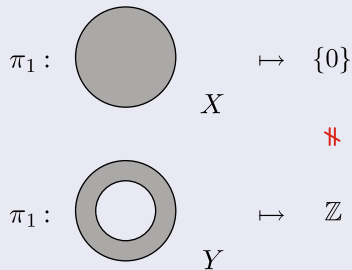


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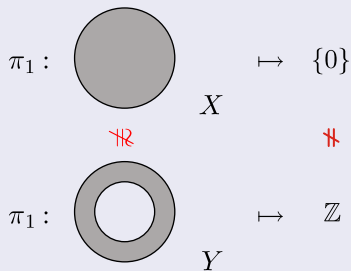


FIG.: $\pi_1(\cdot)$ is a topological invariant.

Definition

Two spaces X and Y are homotopy equivalent or of the same homotopy type if there exist continuous maps $f : X \rightarrow Y$ and $g : Y \rightarrow X$ such that $g \circ f \sim 1_X$ et $f \circ g \sim 1_Y$. $X \simeq Y$.

One writes $X \simeq Y$.

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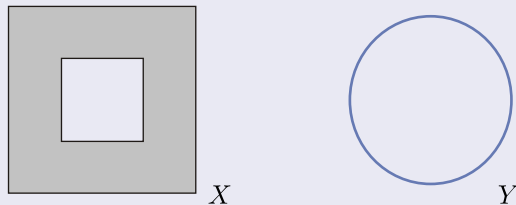


FIG.: $X \simeq Y$

Spaces that are homotopy equivalent.

Definition

Spaces that are homotopy equivalent to a point are called contractible.

$$X \simeq Y.$$

Proposition

Two homeomorphic spaces are of the same homotopy type.

$$X \cong Y \Rightarrow X \simeq Y$$

Proposition

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$$X \cong Y \Rightarrow X \simeq Y$$

Remark

Most of the topological invariant can not distinguished two spaces that are homotopy equivalent.

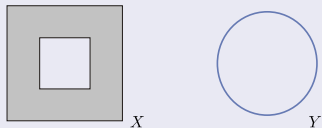


FIG.: $X \simeq Y \Rightarrow \pi_1(X) = \pi_1(Y)$

A triangulation

Definition - Abstract triangulation

Let \mathcal{N} be a finite set of symbols $\{(a^0), (a^1), \dots, (a^n)\}$

An abstract triangulation \mathcal{K} is a subset of the powerset of \mathcal{N} satisfying : $\sigma \in \mathcal{K} \Rightarrow \forall \sigma_0 \subset \sigma, \sigma_0 \in \mathcal{K}$

$$\mathcal{K} = \{(a^0), (a^1), (a^2), (a^3), (a^4), \\ (a^0, a^1), (a^1, a^2), (a^0, a^2), (a^3, a^4), \\ (a^0, a^1, a^2)\}$$

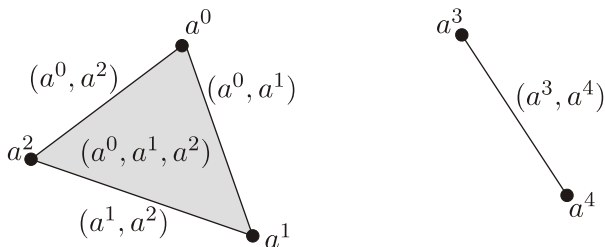


FIG.: A realisation of \mathcal{K} .

$$\mathcal{K} = \{(a^0), (a^1), (a^2), (a^3), (a^4), \\ (a^0, a^1), (a^1, a^2), (a^0, a^2), (a^3, a^4), \\ (a^0, a^1, a^2)\}$$

This will be denoted by $a^0 a^1 a^2 + a^3 a^4$

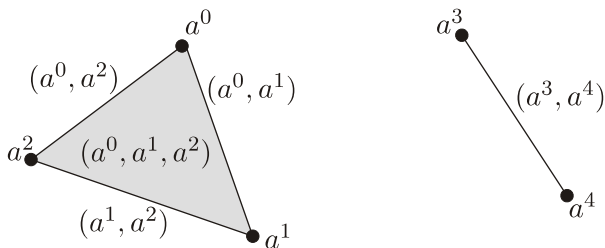
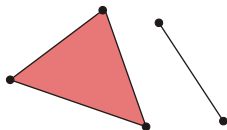
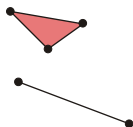


FIG.: A realisation of \mathcal{K} .

Theorem

If $|K_1|$ and $|K_2|$ are two realisations of an abstract triangulation \mathcal{K} , then $|K_1|$ and $|K_2|$ homeomorphic.

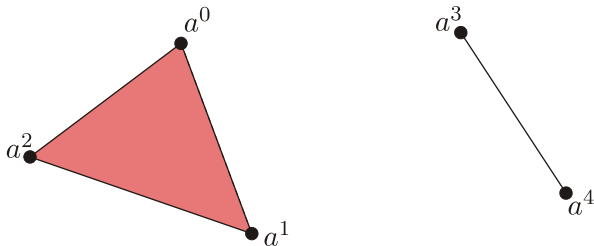
 $|K_1|$  $|K_2|$

Definition

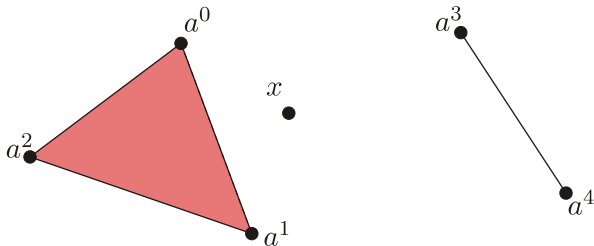
Let \mathcal{K} be an abstract triangulation, an (x) a symbol. One notes by $\mathcal{C}(x, \mathcal{K})$ the set :

$$\mathcal{C}(x, \mathcal{K}) = \{(x)\} \cup \mathcal{K} \cup \bigcup_{\sigma \in \mathcal{K}} (x, \sigma).$$

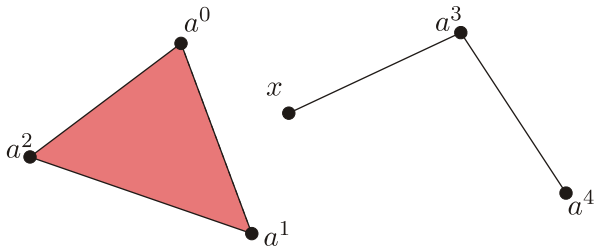
where $(x, \sigma) := (x, a^1, \dots, a^n)$ with $\sigma = (a^1, \dots, a^n) \in \mathcal{K}$.
 $\mathcal{C}(x, \mathcal{K})$ is the *cone* with x as apex and \mathcal{K} as base.



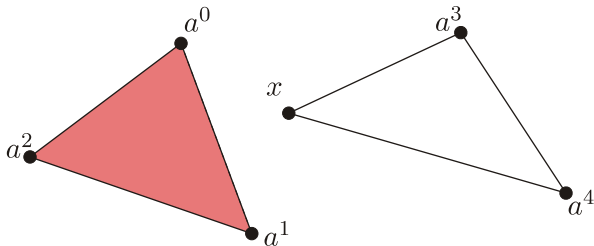
$$\mathcal{C}(x, \mathcal{K}) = \{(x)\} \cup \mathcal{K} \cup \{(x, a^0), (x, a^1), (x, a^2), (x, a^3), (x, a^4), (x, a^0, a^1), (x, a^1, a^2), (x, a^0, a^2), (x, a^3, a^4), (x, a^0, a^1, a^2)\}.$$



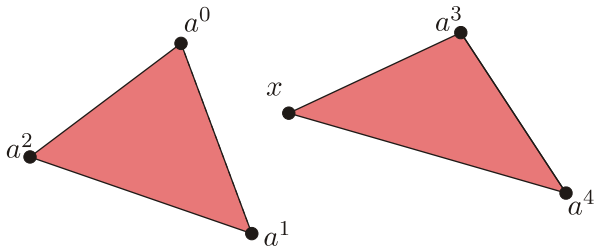
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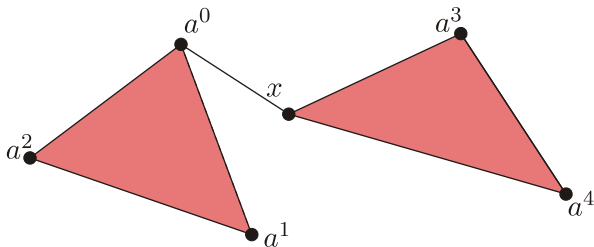
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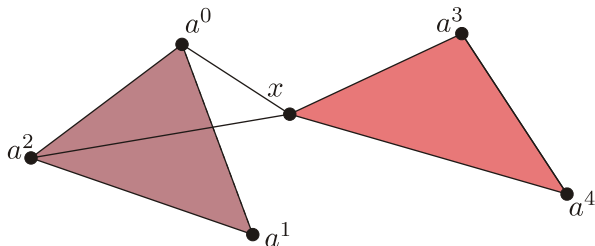
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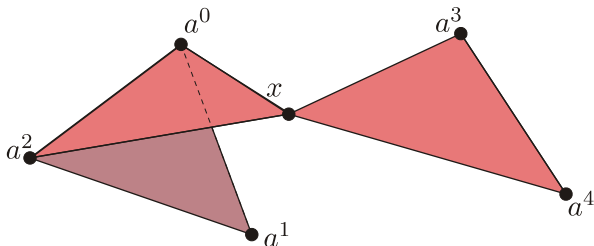
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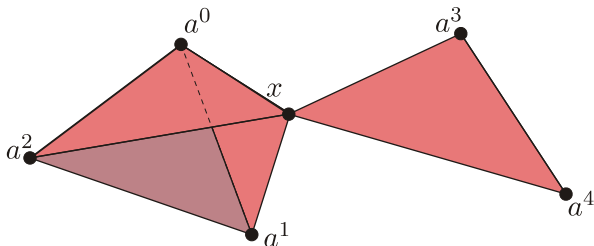
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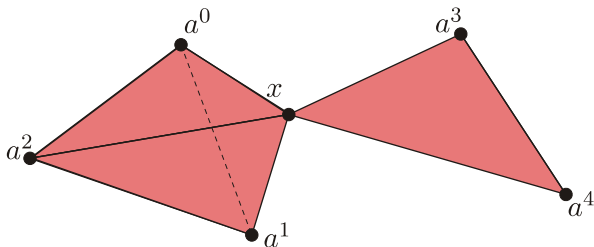
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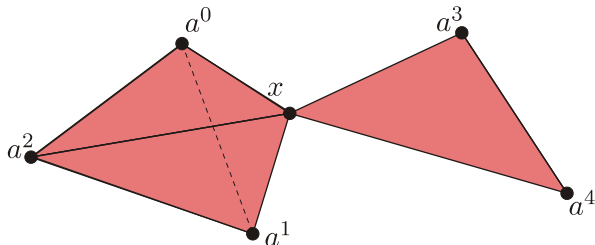


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$$\begin{aligned} \mathcal{C}(x, \mathcal{K}) &= x(a^0 a^1 a^2 + a^3 a^4) \\ &= x a^0 a^1 a^2 + x a^3 a^4 \end{aligned}$$

Property of a cone

A cone is contractible.



Main goal :

Create a triangulation homotopy equivalent to :

$$\mathbb{S} = \bigcup_{i=1}^s \bigcap_{j=1}^{r_i} \{x \in \mathbb{R}^n; f_{i,j}(x) \leq 0\} \text{ where } f_{i,j} \in \mathcal{C}^1(\mathbb{R}^n, \mathbb{R})$$

$$\mathbb{S} = \left\{ (x, y) \in \mathbb{R}^2 \mid \begin{cases} x^2 + y^2 + xy - 2 \leq 0 \\ -x^2 - y^2 - xy + 1 \leq 0 \end{cases} \right\}$$

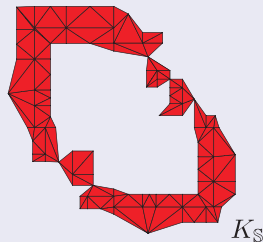
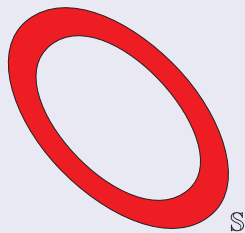


FIG.: Example of a set \mathbb{S} and a triangulation generated by the algorithm Homotopy via Interval Analysis.

1 Create a covering $\{\mathbb{S}_i\}_{i \in I}$ de \mathbb{S} such that

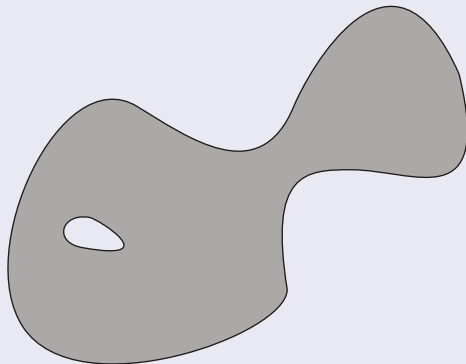
$$\forall J \subset I, \bigcap_{j \in J} \mathbb{S}_j \text{ is contractile or empty}$$

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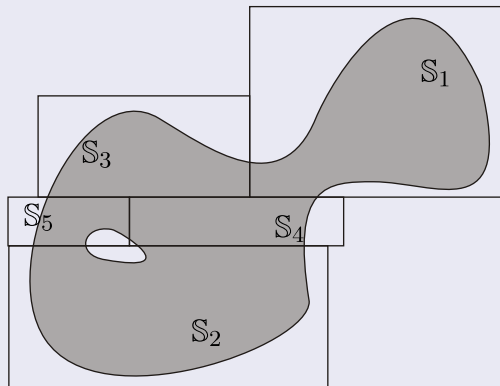
$$\forall J \subset I, \bigcap_{j \in J} \mathbb{S}_j \text{ is contractile or empty}$$

- 2 Create a triangulation homotopy equivalent to \mathbb{S} .

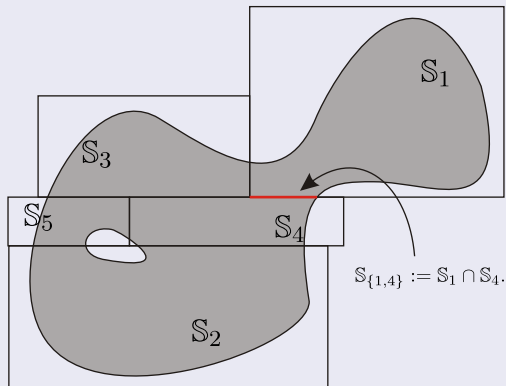
Divide \mathbb{S} with a paving $\{p_i\}_{i \in I}$, ($\mathbb{S}_i := \mathbb{S} \cap p_i$) such that
 $\forall J \subset I, \bigcap_{j \in J} \mathbb{S}_j$ is contractible or empty



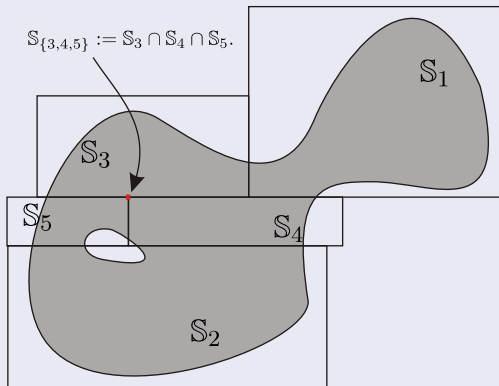
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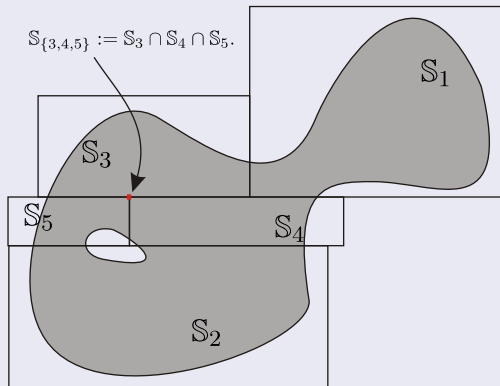
Divide \mathbb{S} with a paving $\{p_i\}_{i \in I}$, ($\mathbb{S}_i := \mathbb{S} \cap p_i$) such that

$$\forall J \subset I, \bigcap_{j \in J} \mathbb{S}_j \text{ is contractible or empty}$$


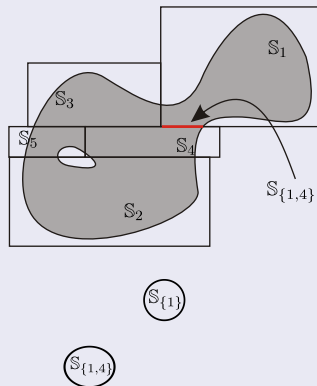
Divide S with a paving $\{p_i\}_{i \in I}$, ($S_i := S \cap p_i$) such that
 $\forall J \subset I, \bigcap_{j \in J} S_j$ is contractible or empty



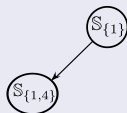
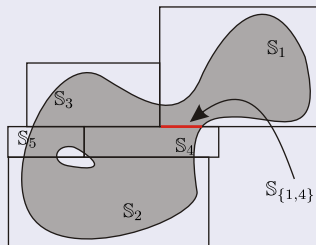
Let $\mathcal{F} = \{S_J, J \subset I, \text{ such that } S_J \text{ is contractible}\}$.



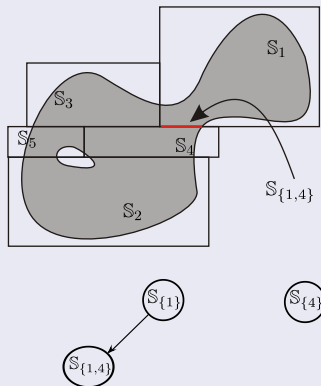
Order \mathcal{F} with inclusion :



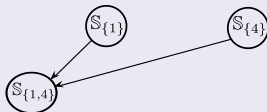
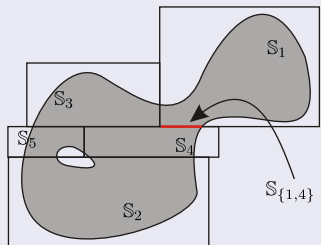
Order \mathcal{F} with inclusion :



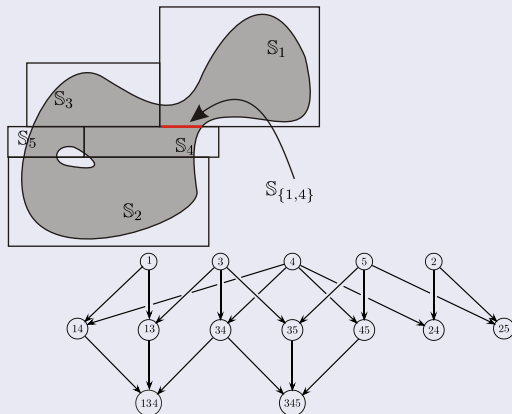
Order \mathcal{F} with inclusion :

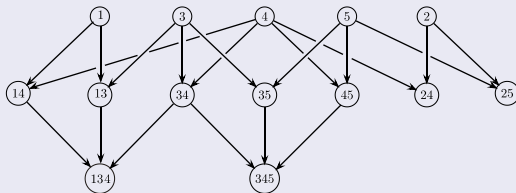


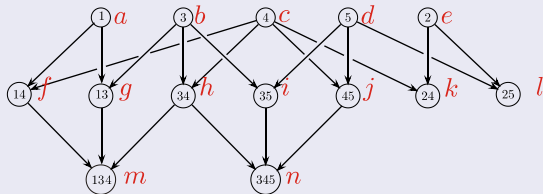
Order \mathcal{F} with inclusion :

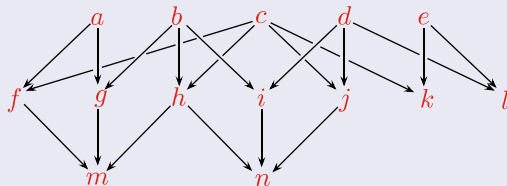


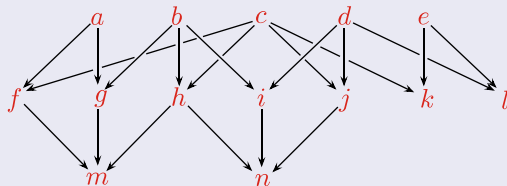
Order \mathcal{F} with inclusion :



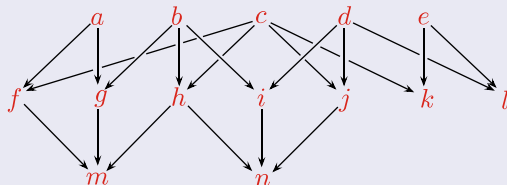




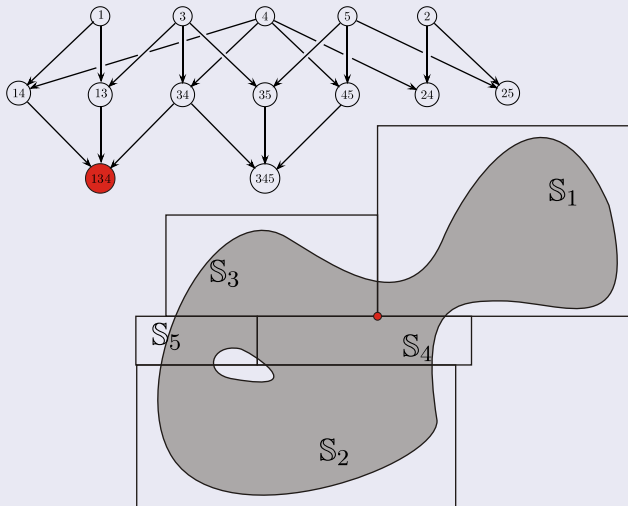


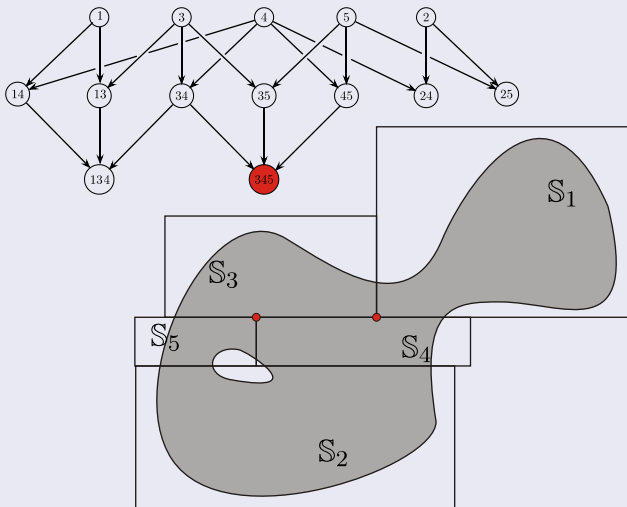


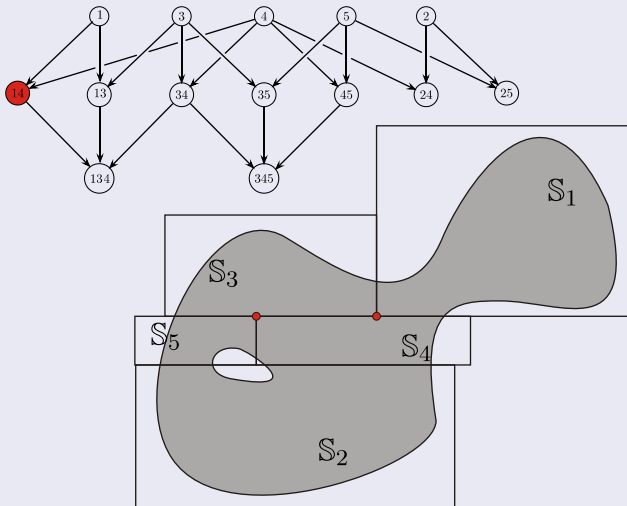
$$\begin{aligned}
 &a(fm+gm)+b(gm+h(m+n)+in)+ \\
 &\quad +c(fm+h(m+n)+jn+k)+d(in+jn+l)+e(k+l)
 \end{aligned}$$

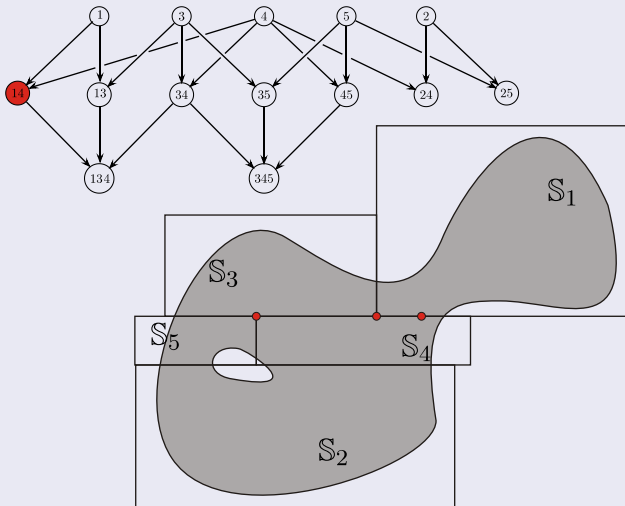


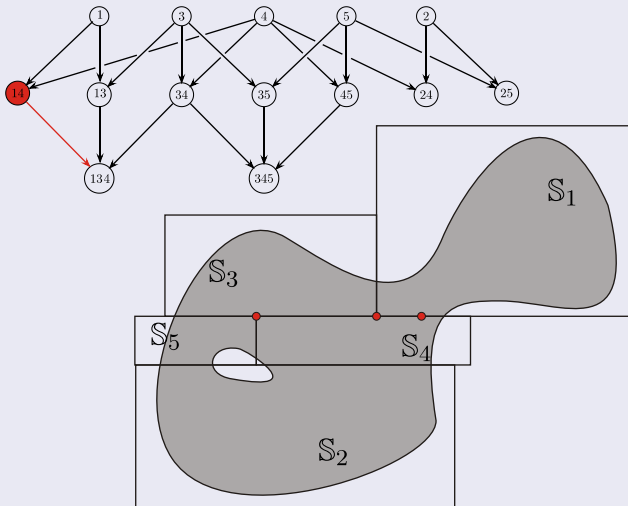
$$\begin{aligned}
 & a(fm+gm)+b(gm+h(m+n)+in)+ \\
 & \quad +c(fm+h(m+n)+jn+k)+d(in+jn+l)+e(k+l) \\
 & = \\
 & a fm+agm+bgm+bhm+bhn+bin+ \\
 & \quad +cfm+chm+chn+cjn+ck+din+djn+dl+ek+el
 \end{aligned}$$

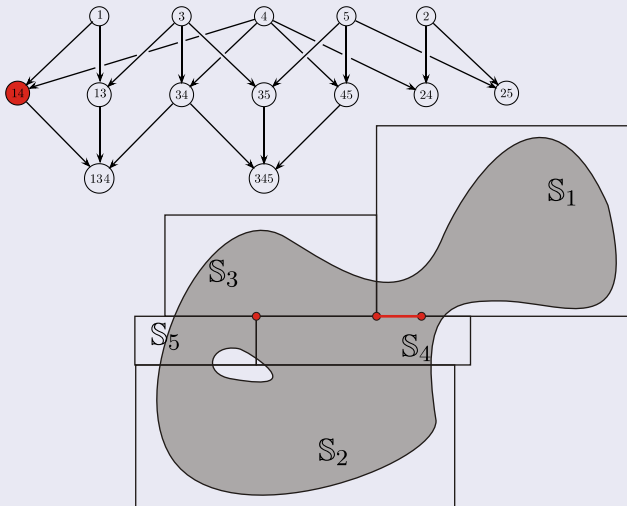


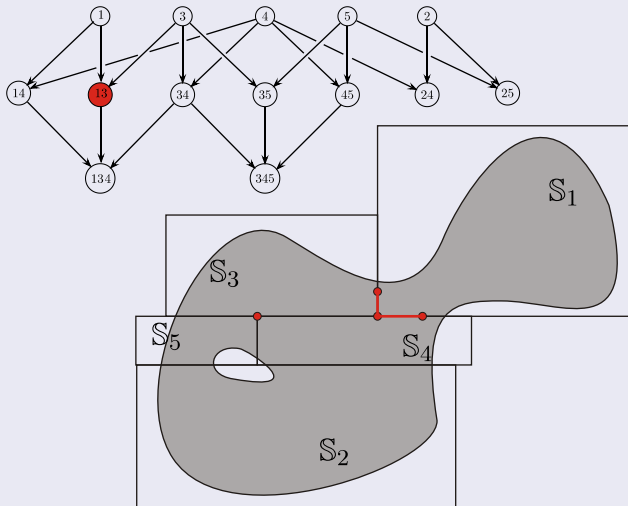


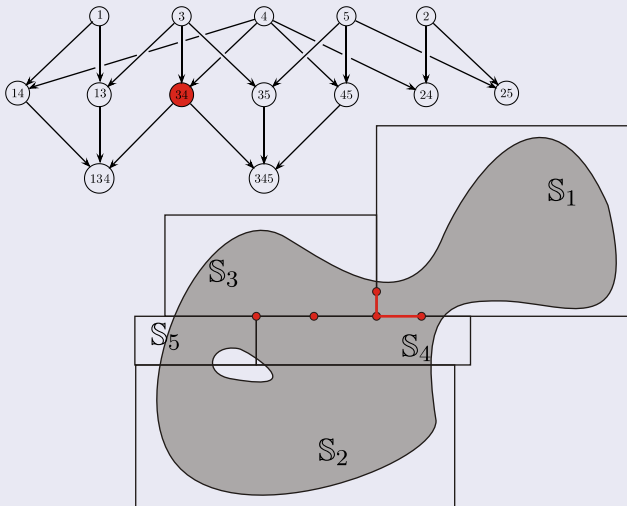


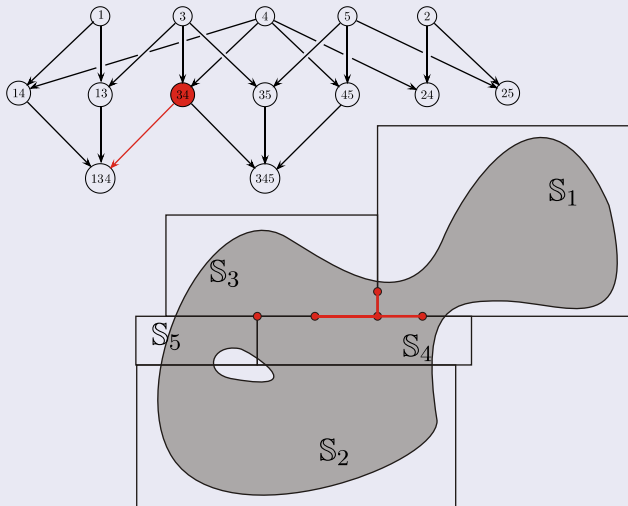


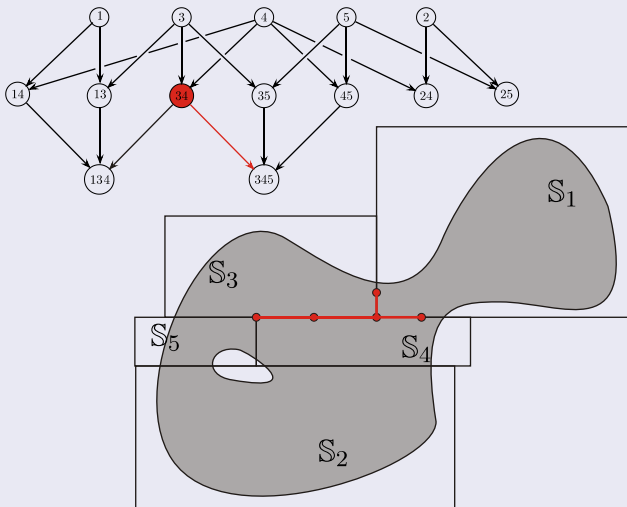


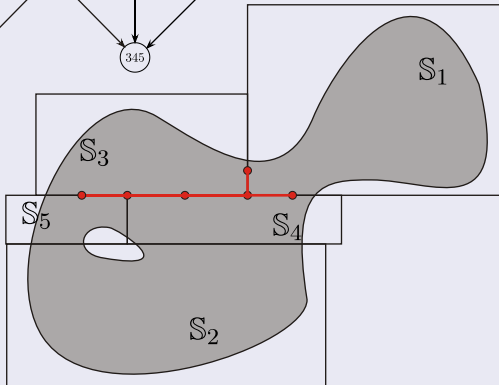
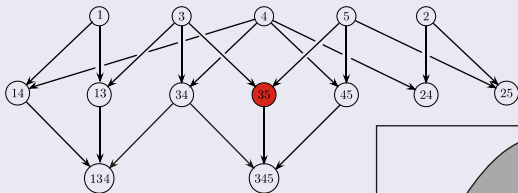


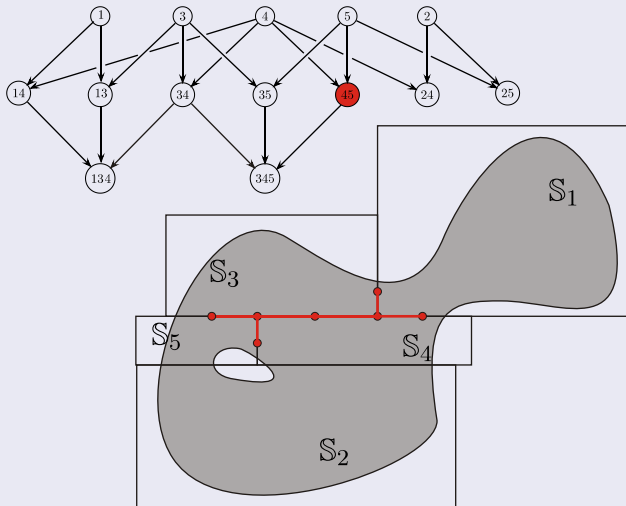


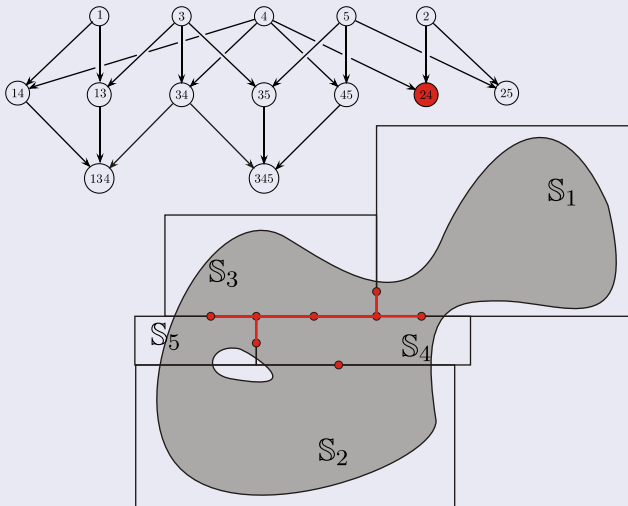


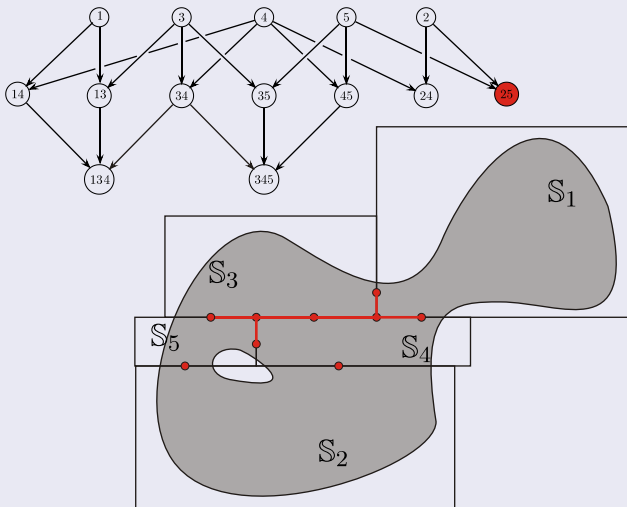


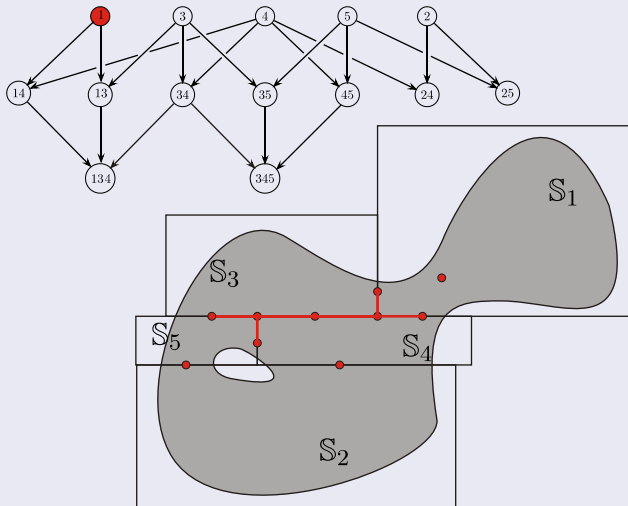


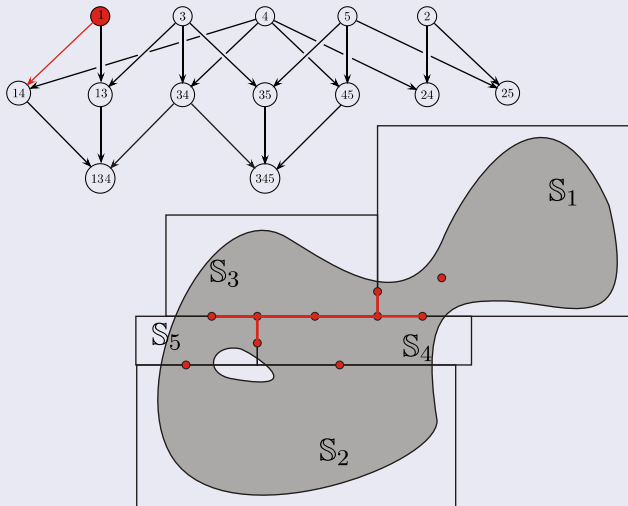


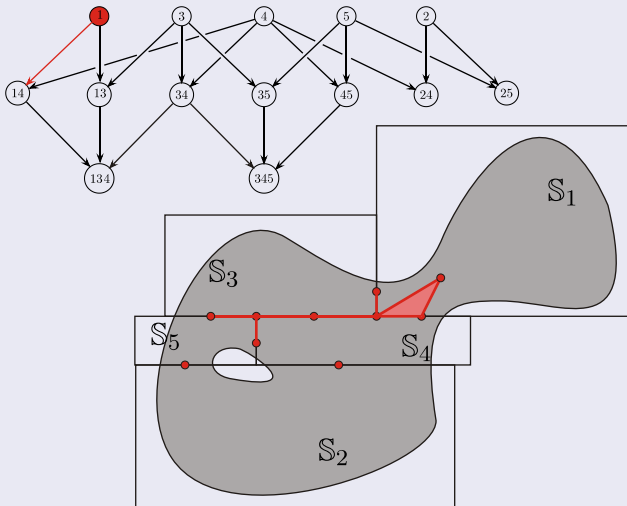


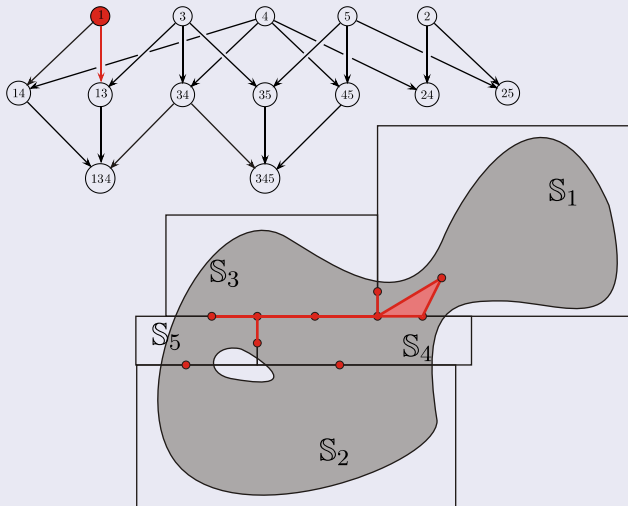


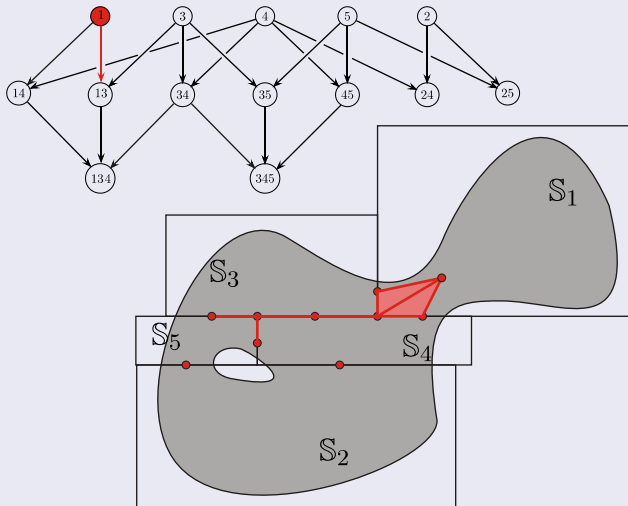


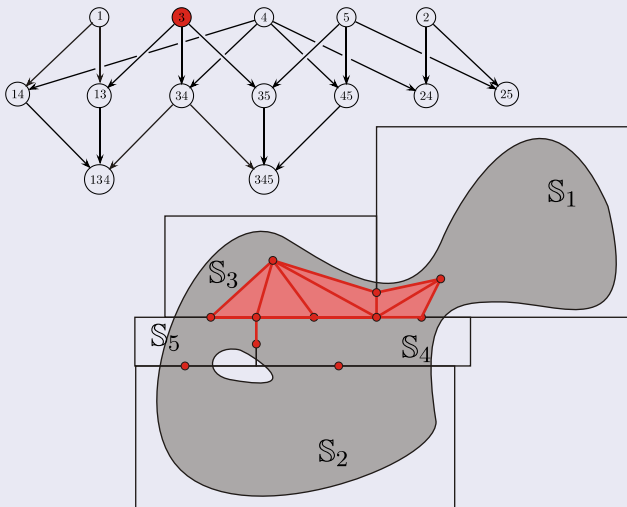


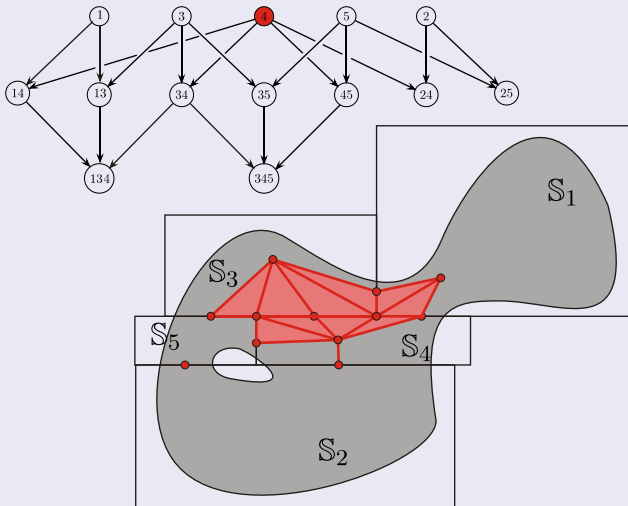


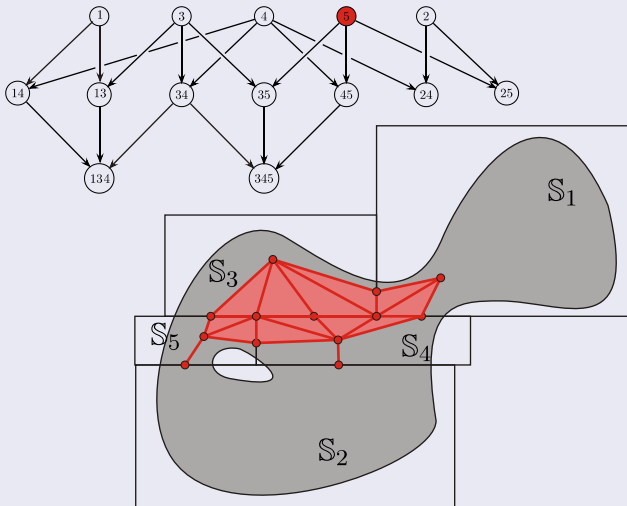


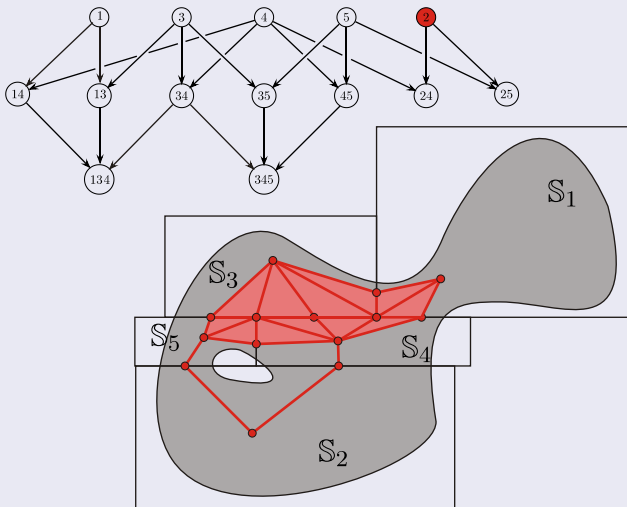












- CIA : Connected components via Interval Analysis
<http://www.istia.univ-angers.fr/~delanoue/>

- CIA : Connected components via Interval Analysis
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- HIA : Homotopy type via Interval Analysis
<http://www.istia.univ-angers.fr/~delanoue/>

What I am doing now

Stability and dynamical system with

- interval analysis.

What I am doing now

Stability and dynamical system with

- interval analysis.
- graph theory.

What I am doing now

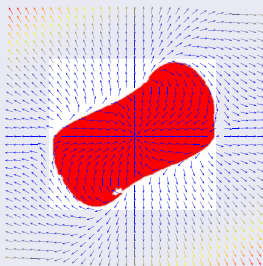
Stability and dynamical system with

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What I am doing now

Stability and dynamical system with

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- Merci pour votre attention !

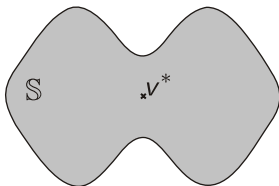
Theorem

If $\mathbb{S} = \{x \in D \subset \mathbb{R}^n / f(x) \leq 0\}$ where f is a C^1 function from D to \mathbb{R} , D a convex set, v^* be in \mathbb{S} and if

$$f(x) = 0, Df(x).(x - v^*) \leq 0, x \in D$$

is inconsistent then v^* is star a for \mathbb{S} .

(1) est inconsistent $\Leftrightarrow \forall x \in D, f(x) = 0 \Rightarrow \partial f(x).(x - v^*) > 0$



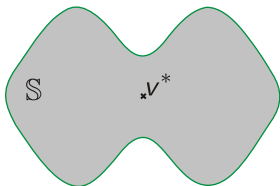
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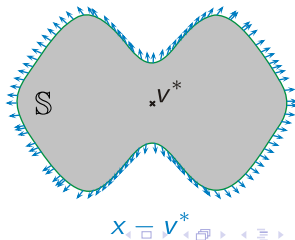
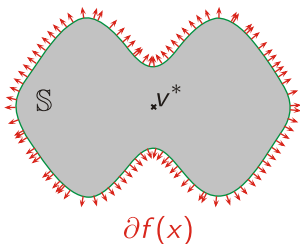
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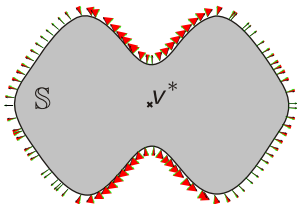
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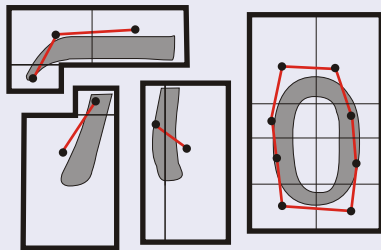


Corollaire

Let \mathcal{G}_S be a star-spangled graph of a set S .

\mathcal{G}_S has the same number of connected components than S . i.e.

$$\pi_0(S) = \pi_0(\mathcal{G}_S).$$



▶ Back

