

# Attraction domain and nonlinear dynamical system using interval analysis.

Nicolas Delanoue - Luc Jaulin

SWIM08 : a Small Workshop on Interval Methods

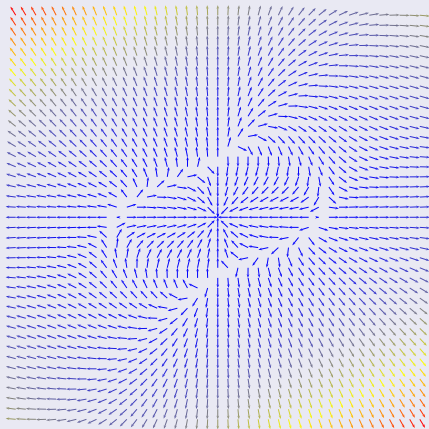
Montpellier 2008

# Outline

- 1 Introduction - Dynamical system
  - Equilibrium state - Stability
  - Attraction Domain
- 2 Lyapunov theory
  - Positivity
  - Lyapunov Theory
  - Algorithm A
- 3 Discretization
  - Algorithm B

Compute the attraction domain of an asymptotically stable point

$$\begin{cases} \dot{x} = f(x) \\ x \in \mathbb{R}^n \end{cases}, f \in C^\infty(\mathbb{R}^n, \mathbb{R}^n).$$



Let us denote by  $\{\varphi^t : \mathbb{R}^n \rightarrow \mathbb{R}^n\}_{t \in \mathbb{R}}$  the flow, i.e.

$$\left. \frac{d}{dt} \varphi^t x \right|_{t=0} = f(x) \text{ and } \varphi^0 = Id \quad (1)$$

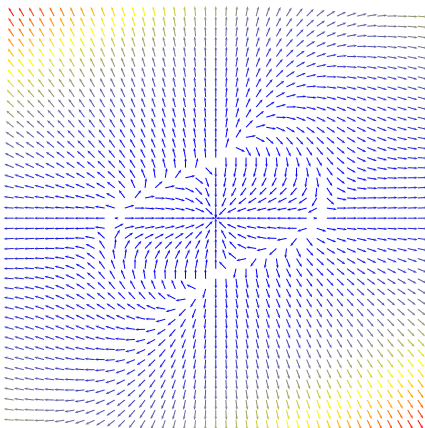
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The function  $t \mapsto \varphi^t x$  is the solution of  $\dot{x} = f(x)$  satisfying  $x(0) = x$ .

## Definition

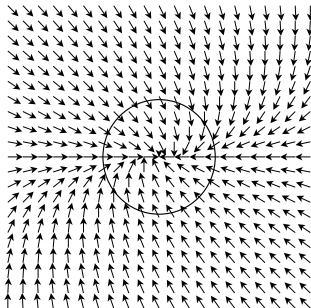
A point  $x \in \mathbb{R}^n$ ,  $x$  is an *equilibrium state* if  $f(x) = 0$  i.e.  
 $\varphi^t(x) = x, \forall t \in \mathbb{R}$ .



## Definition

A set  $D$  is *stable* if :

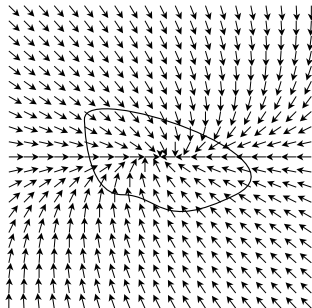
$$\varphi^{\mathbb{R}^+}(D) \subset D$$



## Definition

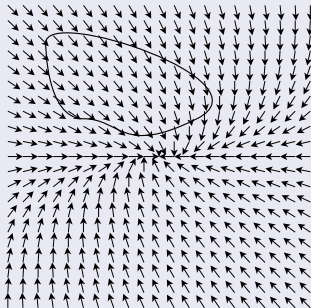
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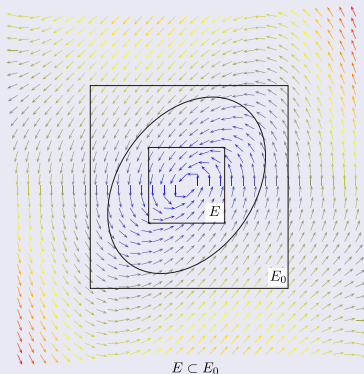


## Example of a non stable set



## Definition

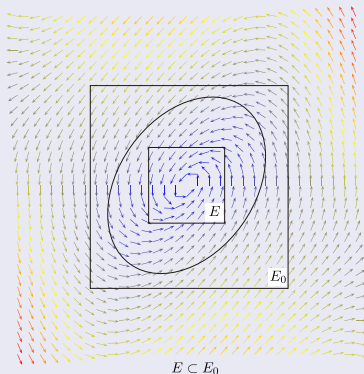
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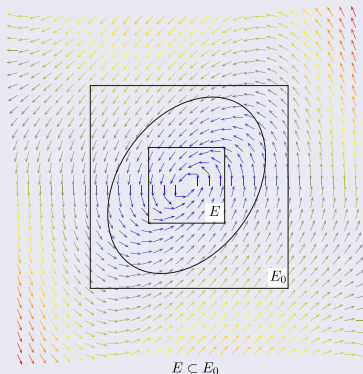
- $\varphi^{\mathbb{R}^+}(E) \subset E_0$



## Definition

An equilibrium state  $x_\infty$  is *asymptotically  $(E, E_0)$ -stable* if

- $\varphi^{\mathbb{R}^+}(E) \subset E_0$
- $\varphi^\infty(E) = \{x_\infty\}$



## Definition

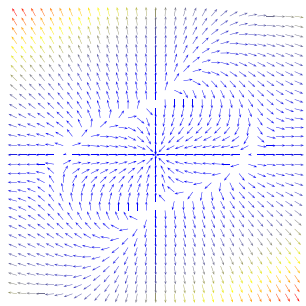
The attraction domain of  $x_\infty$  is the set

$$A_{x_\infty} = \{x \in D \mid \varphi^\infty(x) = x_\infty\}.$$

*Solver.*

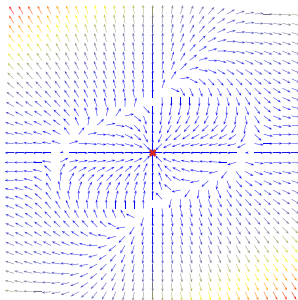
Compute the attraction domain  $A_{x_\infty}$ .

- 1
- 2
- 3



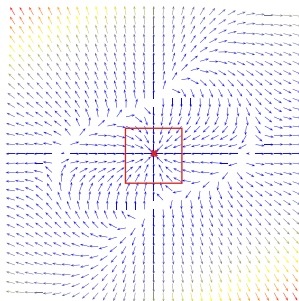
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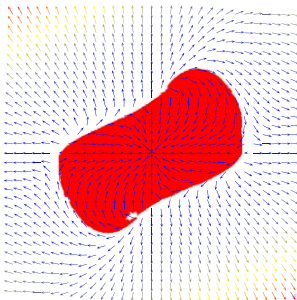
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- 1 Show that there exists an unique equilibrium point  $x_\infty$ ,
- 2 Prove that  $x_\infty$  is asymptotically stable and compute a neighborhood of  $x_\infty$  included in the attraction domain.
- 3 Discretize the vector field to compute a sequence  $A_n$  such that  $A_n \rightarrow_{n \rightarrow \infty} A_{x_\infty}$  where  $A_{x_\infty}$  is the attraction domain of  $x_\infty$ . (Alg. B)



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A proof that  $\forall x \in [x], f(x) \geq 0$ .

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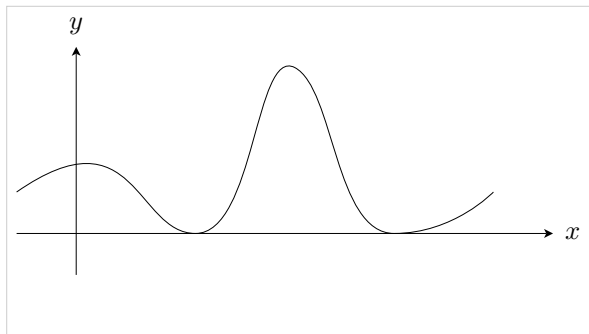
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- $\forall x \in [x], f(x) = 0$  : algebra calculus.

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- $\forall x \in [x], f(x) > 0$  : interval analysis.
- $\forall x \in [x], f(x) = 0$  : algebra calculus.
- In other cases ?



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In the cases where function are not polynomials.



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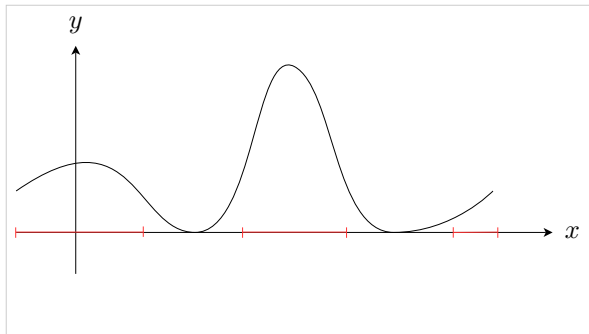
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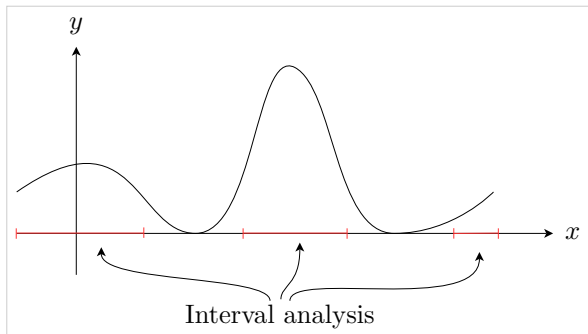
## Interval analysis is not enough ...

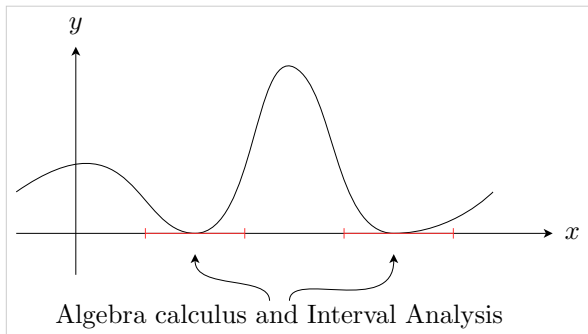
In the general case, one only has :

$$f([x]) \not\subseteq [f]([x]).$$

- multiple occurrence of variables.
- outward rounding.







## Theorem

Let  $x_0 \in E$  where  $E$  is a convex set of  $\mathbb{R}^n$ , and  $f \in \mathcal{C}^2(\mathbb{R}^n, \mathbb{R})$ . One has :

If

- 1  $\exists x_0$  such that  $f(x_0) = 0$  and  $Df(x_0) = 0$ .
- 2  $\forall x \in E, D^2f(x) > 0$ .

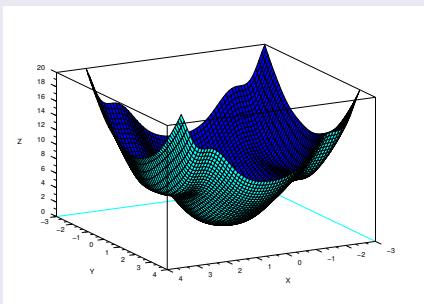
then  $\forall x \in E, f(x) \geq 0$ .

## Example

To prove that  $f(x) \geq 0, \forall x \in [-1/2, 1/2]^2$

where  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  is defined by

$$f(x, y) = -\cos(x^2 + \sqrt{2} \sin^2 y) + x^2 + y^2 + 1.$$





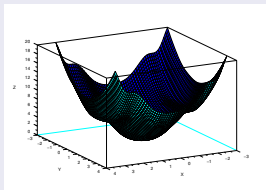
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- ① One has :  $f(0, 0) = 0$  and  $\nabla f(0, 0) = 0$

$$\nabla f(x, y) = \begin{pmatrix} 2x(\sin(x^2 + \sqrt{2} \sin^2 y) + 1) \\ 2\sqrt{2} \cos y \sin y \sin(\sqrt{2} \sin^2 y + x^2) + 2y \end{pmatrix}.$$



$$\nabla^2 f = \begin{pmatrix} a_{1,1} & a_{1,2} \\ a_{2,1} & a_{2,2} \end{pmatrix} = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

$$a_{1,1} = 2 \sin(\sqrt{2} \sin^2 y + x^2) + 4x^2 \cos(\sqrt{2} \sin^2 y + x^2) + 2.$$

$$a_{2,2} = -2\sqrt{2} \sin^2 y \sin(\sqrt{2} \sin^2 y + x^2) + 2\sqrt{2} \cos^2 y \sin(\sqrt{2} \sin^2 y + x^2) + 8 \cos^2 y \sin^2 y \cos(\sqrt{2} \sin^2 y + x^2) + 2.$$

$$a_{1,2} = a_{2,1} = 4\sqrt{2}x \cos y \sin y \cos(\sqrt{2} \sin^2 y + x^2).$$

Evaluation with interval analysis gives :  $\forall x \in [-1/2, 1/2]^2$ ,  
 $\nabla^2 f(x) \subset [A]$

$$[A] = \begin{pmatrix} [1.9, 4.1] & [-1.3, 1.4] \\ [-1.3, 1.4] & [1.9, 5.4] \end{pmatrix}.$$

One only has to check that :  $\forall A \in [A]$ ,  $A$  is positive definite.

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### Definition

A symmetric matrix  $A$  is positive definite if

$$\forall x \in \mathbb{R}^n - \{0\}, x^T A x > 0$$

$S^{n+}$  denote the set of  $n \times n$  symmetric positive definite matrices.

## Definition

A set of symmetric matrices  $[A]$  is an interval of symmetric matrices if :

$$[A] = \{(a_{ij})_{ij}, a_{ij} = a_{ji}, a_{ij} \in [a]_{ij}\}$$

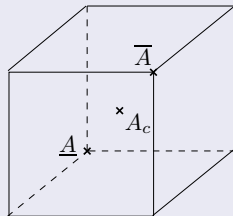
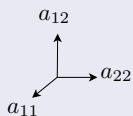
i.e.

$$[\underline{A}, \bar{A}] = \{A \text{ symmetric}, \underline{A} \leq A \leq \bar{A}\}.$$

## Example

Using  $\mathbb{R}^2$  is a symmetric matrix  $A$

$$A = \begin{pmatrix} a_{1,1} & a_{1,2} \\ a_{1,2} & a_{2,2} \end{pmatrix}$$

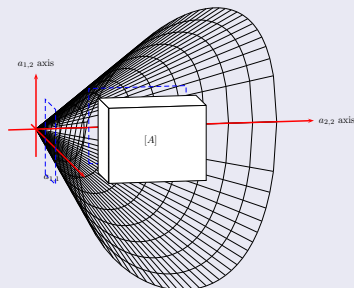


## Remark - Rohn

Let  $V([A])$  finite set of corners of  $[A]$ . Since  $S^{n+}$  and  $[A]$  are convex subset of  $S^n$  :

$$[A] \subset S^{n+} \Leftrightarrow V([A]) \subset S^{n+}$$

$S^n$  is a vector space of dimension  $\frac{n(n+1)}{2}$ .  $\#V([A]) = 2^{\frac{n(n+1)}{2}}$ .

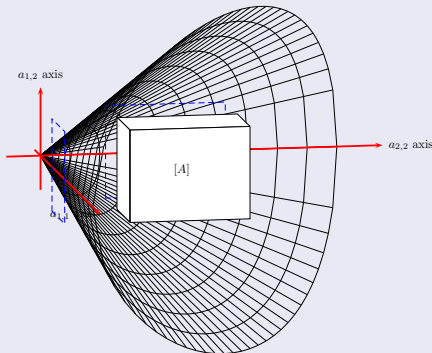


## Theorem- Adefeld

Let  $[A]$  a symmetric interval matrix

and  $C = \{z \in \mathbb{R}^n \text{ tel que } |z_i| = 1\}$

If  $\forall z \in C, A_z = A_c + \text{Diag}(z)\Delta\text{Diag}(z)$  is positive definite  
then  $[A]$  is positive definite.





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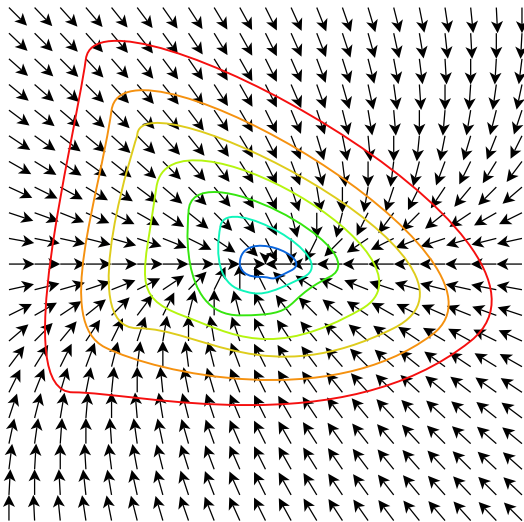
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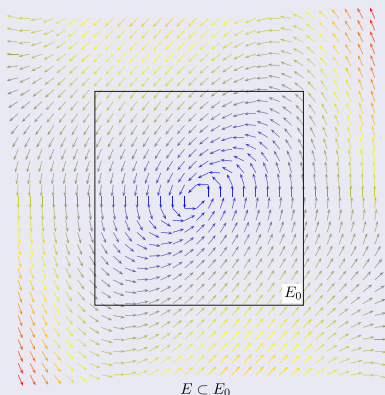
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- 3  $\langle \nabla L(x), f(x) \rangle < 0, \forall x \in E - \{x_\infty\}$



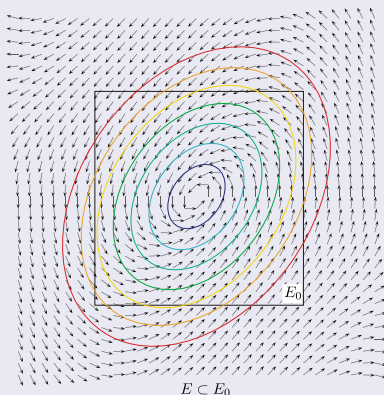
## Lyapunov theorem

Let  $E_0$  a compact subset of  $\mathbb{R}^n$  and  $x_\infty \in E_0$ .  
If  $L : E_0 \rightarrow \mathbb{R}$  is of Lyapunov ( $\dot{x} = f(x)$ ) then  
there exists a subset  $E \subset E_0$  such that  $x_\infty$  is asymptotically  
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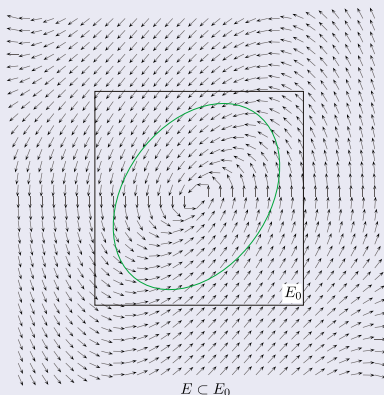
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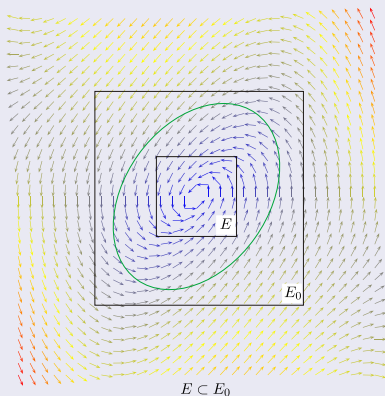
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In the linear case :

$$\dot{x} = Ax \quad (2)$$

With  $L = x^T W x$ ,  $W \in S^n$

one has  $\langle \nabla L(x), f(x) \rangle = x^T (A^T W + W A)x$ .

## Lyapunov conditions

$S^n$  is the set of symmetric matrices.

$S^{n+}$  is the set of positive definite symmetric matrices.

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### Lyapunov conditions

- 1  $W \in S^{n+}$ .
- 2  $-(A^T W + W A) \in S^{n+}$ .

$S^n$  is the set of symmetric matrices.

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## Theorem

Let  $\dot{x} = Ax$ ,  $O$  is asymptotically stable if and only if the solution  $W$  of the equation

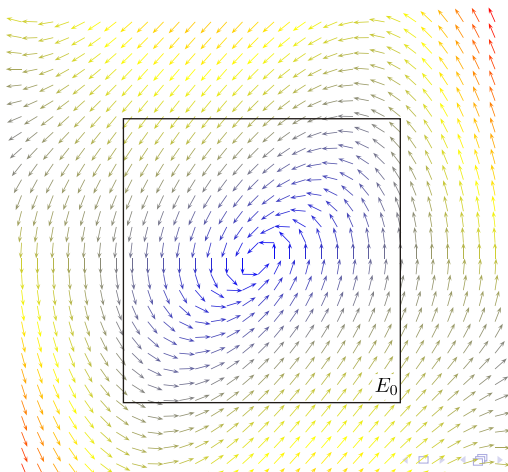
$$A^T W + WA = -I$$

is positive definite.

## Algorithm A

Step 1. Prove that  $E_0$  contains a unique equilibrium state.

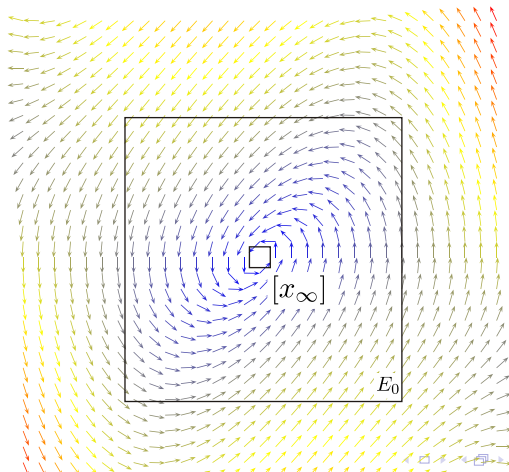
Step 2. Find  $[x_\infty] \subset E_0$  such that  $x_\infty \in [x_\infty]$ .



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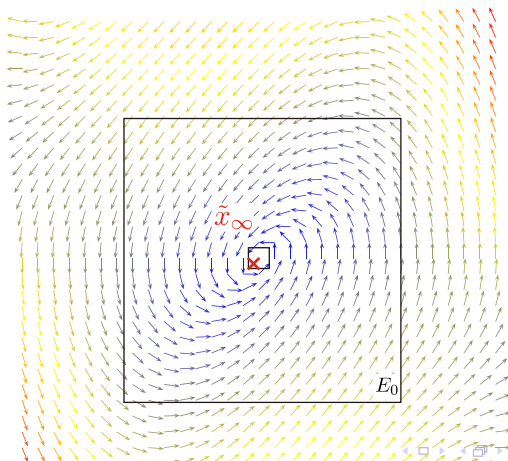
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## Algorithm A

Step 3. Linearize around  $x_\infty$  with  $\tilde{x}_\infty$  ( $\tilde{x}_\infty \in [x_\infty]$ ):

$$\overline{(x - x_\infty)} = Df(\tilde{x}_\infty)(x - x_\infty).$$

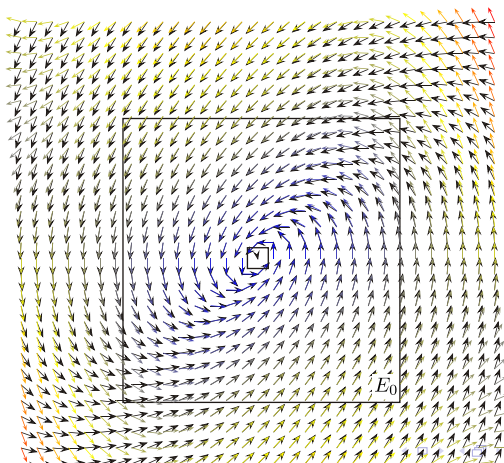




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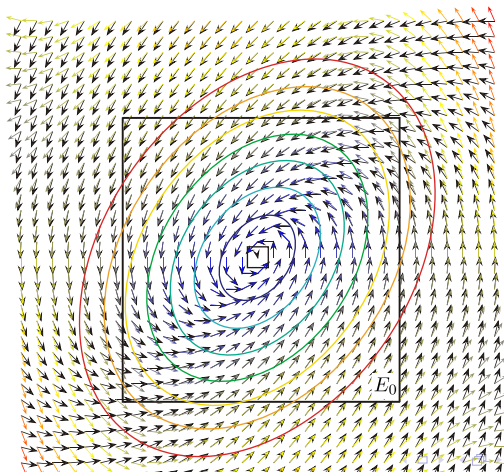
Step 3. Linearize around  $x_\infty$  with  $\tilde{x}_\infty$  ( $\tilde{x}_\infty \in [x_\infty]$ ) :

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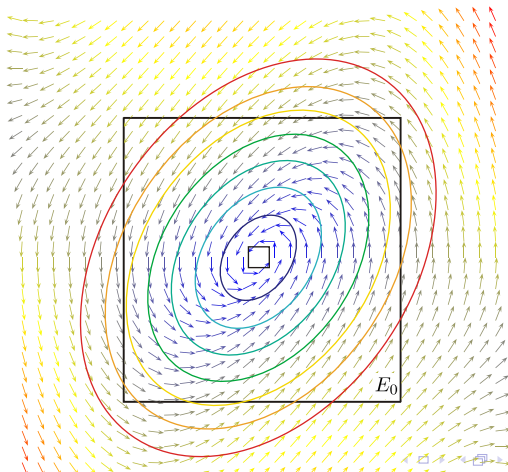
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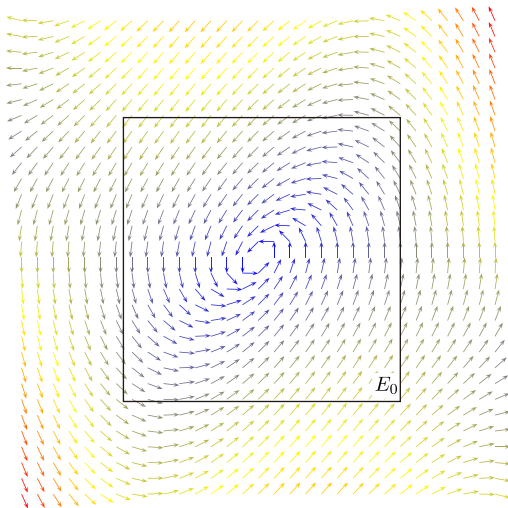
Step 4. Find a Lyapunov function  $L_{x_\infty}$  for the linear system  $Df(\tilde{x}_\infty)$ .

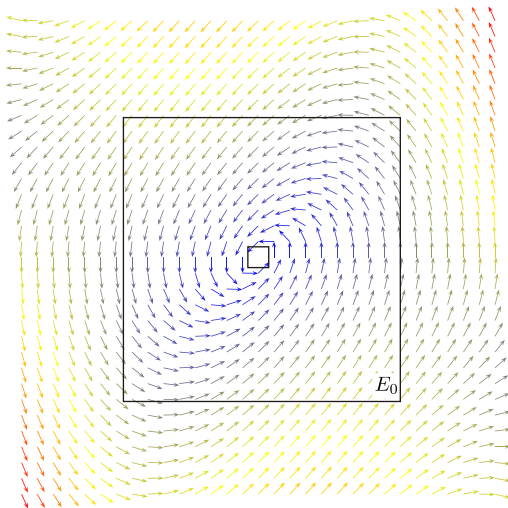


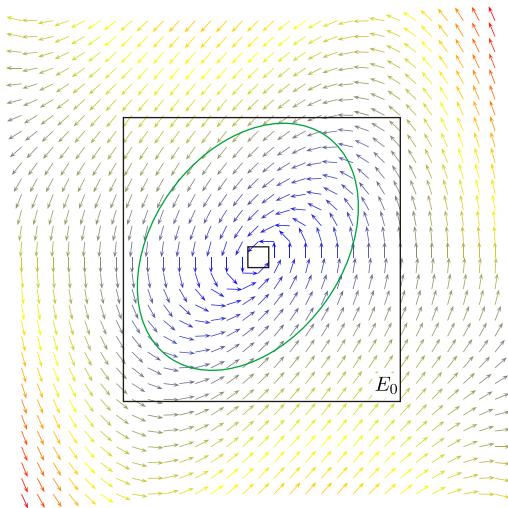
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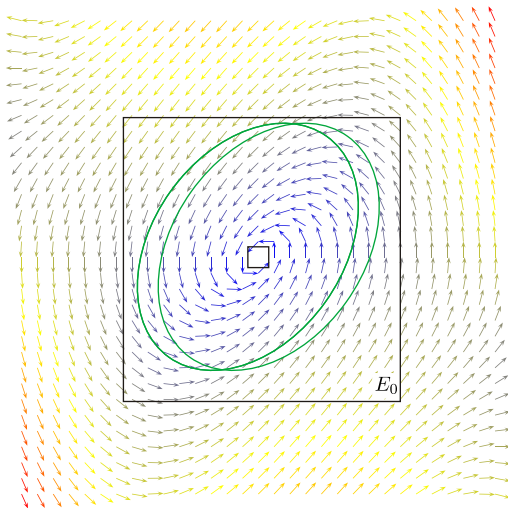
Step 5. Check that  $L_{x_\infty}$  is of Lyapunov for the non linear system  $\dot{x} = f(x)$ .

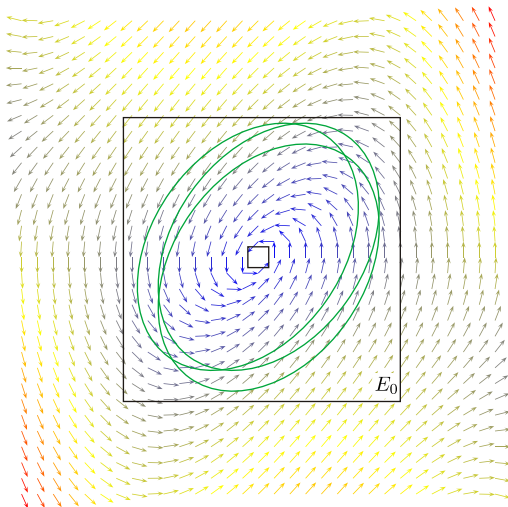




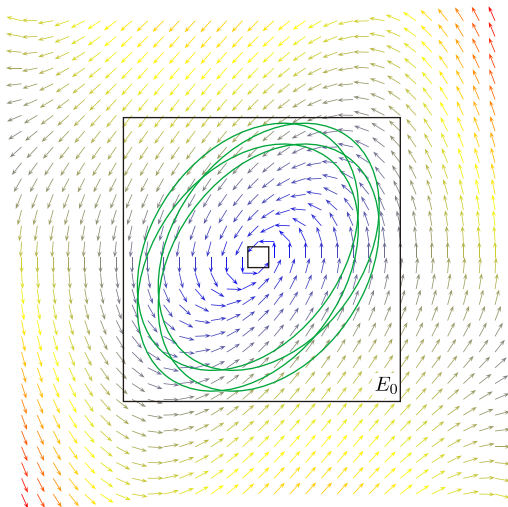


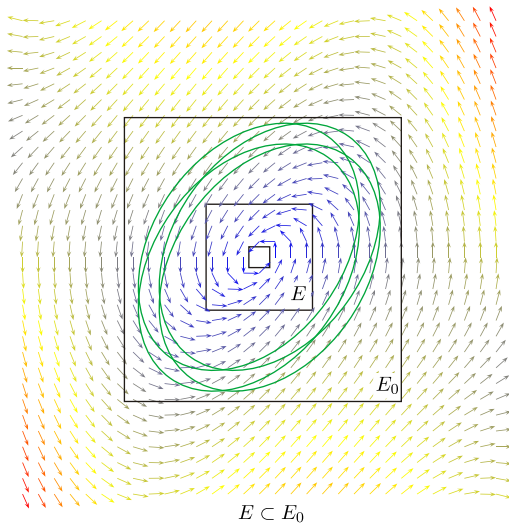






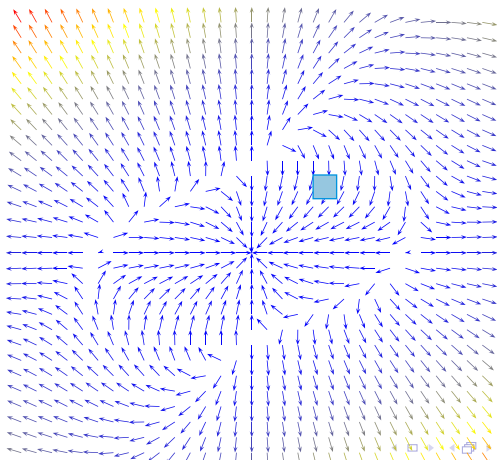






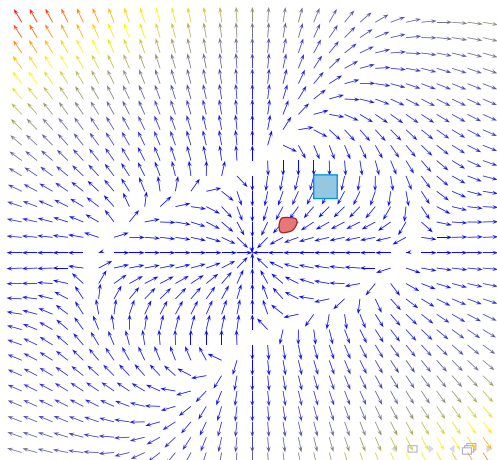
## Picard-Lindelöf

Let  $\dot{x} = f(x)$  and  $t \in \mathbb{R}$ , there exists a guaranteed method able to compute an inclusion function for  $\varphi^t : \mathbb{R}^n \rightarrow \mathbb{R}^n$ .



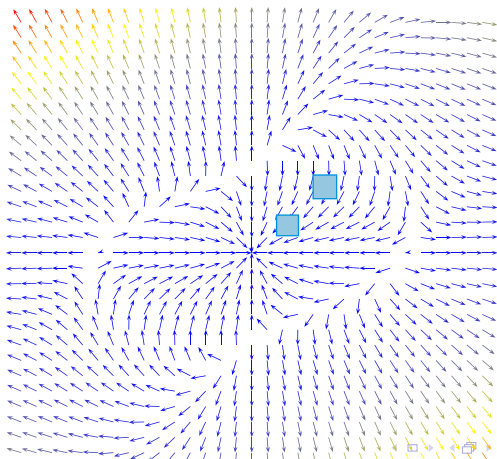
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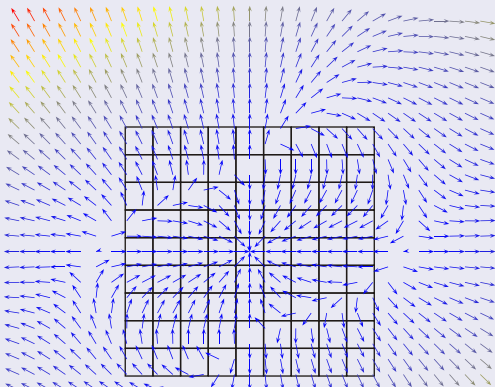
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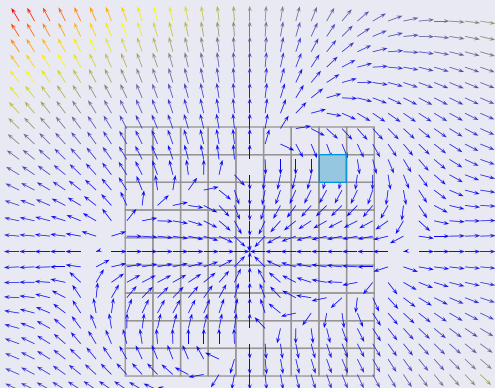
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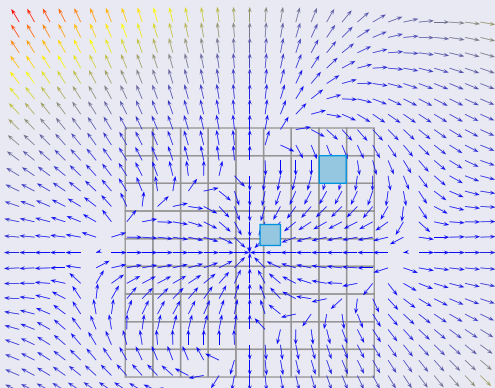
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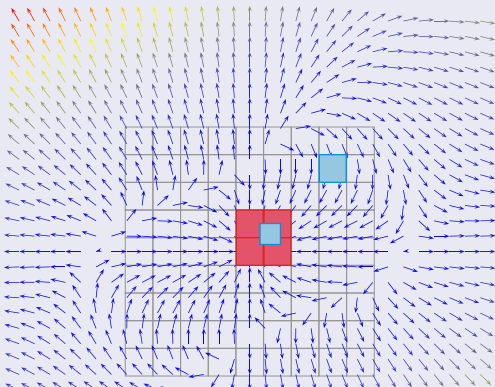




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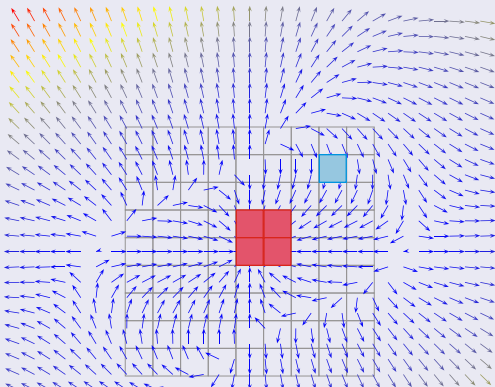
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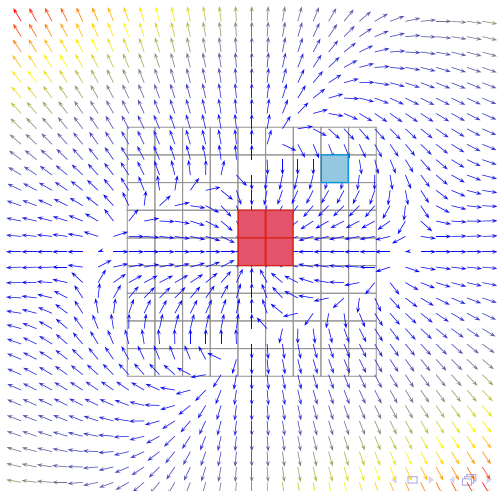
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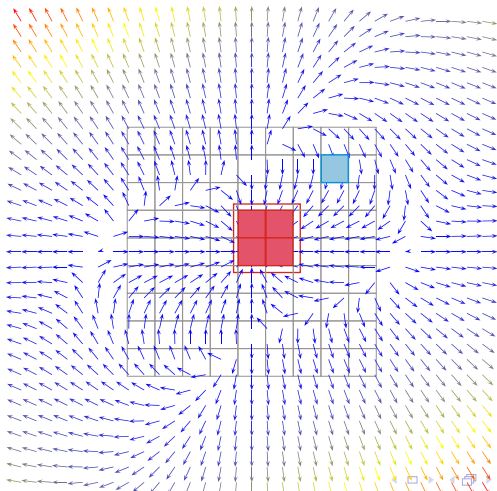
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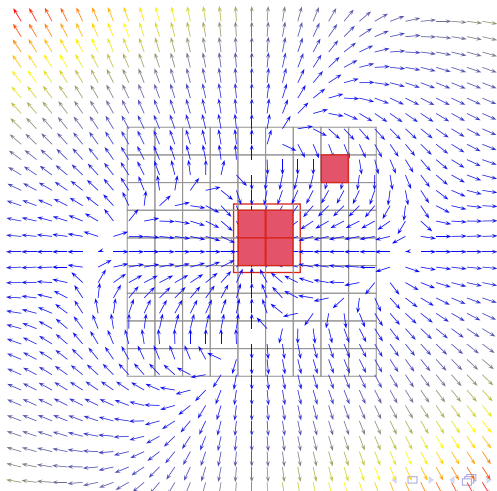
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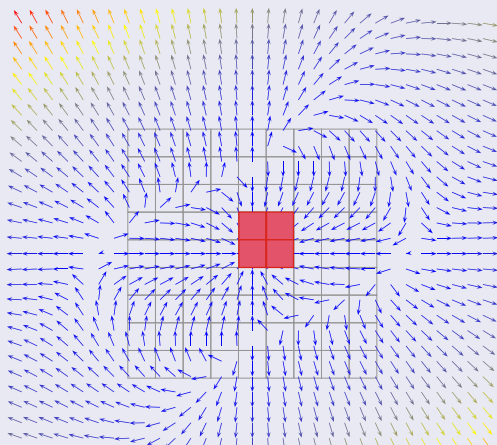
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  - 3 For each  $i$  of  $I$ , if

$$\forall j \in I, i \mathcal{R} j \Rightarrow S_j \subset A$$

then  $A := A \cup S_i$ .

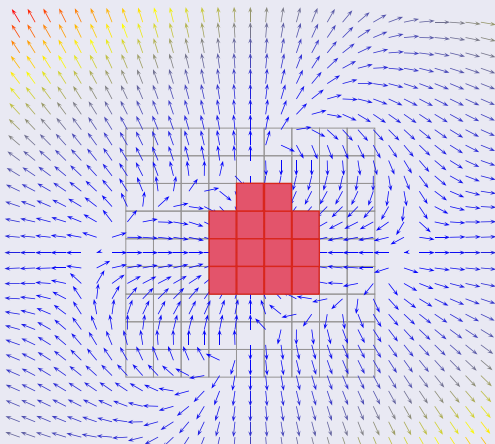
## Example

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} x(x^2 - xy + 3y^2 - 1) \\ y(x^2 - 4yx + 3y^2 - 1) \end{pmatrix}$$



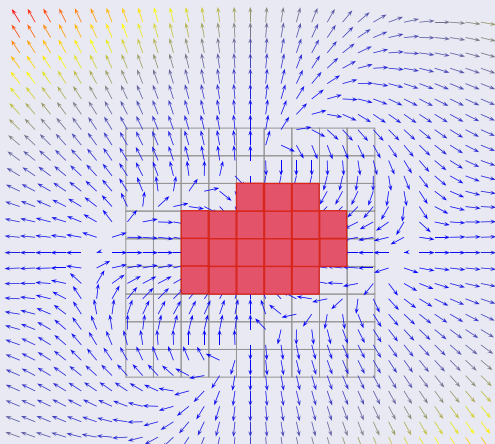
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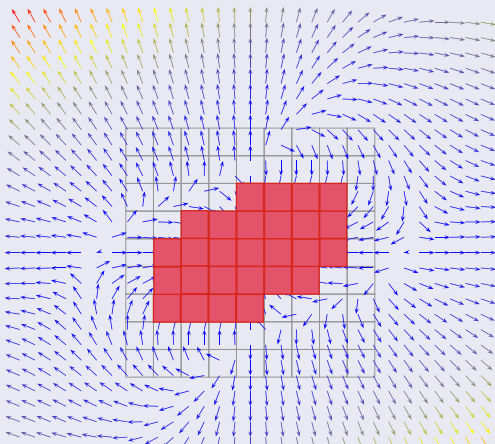
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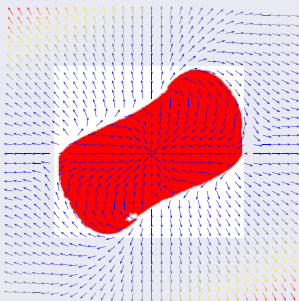
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- Thank you for your attention !